COMPUTER AIDED ITERATIVE DESIGN – A FUTURE TREND IN COMPUTER AIDED ENGINEERING SOFTWARE

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ABSTRACT: Typical engineering design processes involve an initial design, followed by iterations of analyses, interpreting and evaluating analyses results, and proposing new design or modifying existing design. The final design often results from intuitions obtained during this iterative process. Most computer-aided engineering (CAE) software focuses on the computer-aided analysis by advancing capabilities in pre-processing, computation, and post-processing. However, little attention has been paid to the support of the aforementioned iterative design process, which is the common practice in engineering design. Authors believe the next-generation CAE software should evolve into CAID (Computer-Aided Iterative Design) software to help engineers go through the iterative design process and develop better engineering designs. In this paper, key software requirements for the iterative design process are discussed in this work. Furthermore, prototype CAID software developed using C++, Qt, and VTK is demonstrated. The analyzing capability of the developed CAID software is based on an essential software framework for meshfree methods (ESFM). The proposed CAID concept and prototype software shall provide guidelines for future CAE software development.

Keywords: Computer-aided Design, Computer-aided Engineering, Meshfree, Meshless

1. INTRODUCTION
Computer-aided engineering (CAE) software such as ABAQUS and ANSYS, among many others, has become one of the essential tools in engineering designs. By using CAE software, engineering designs can be objectively evaluated and their performances can be predicted to see if requirements can be fulfilled. In general, designs must go through an iterative process depicted in Fig. 1:

CAE software generally divides an engineering analysis into three steps: 1) pre-processing, 2) analysis/calculation, and 3) post-processing. Pre-processing prepares computer models that can be understood by the calculation module; analysis/calculation computes solutions based on user-defined procedures in the prepared model; post-processing visualizes the computed solutions to help users check performances and gain insights to the analyzed problem. Most CAE software has invested significant effort to perfect these three steps, i.e. the upper part of Fig. 1, to help users easily and intuitively create models and generates meshes in finite element methods (FEM), to incorporate and to advance analyzing capabilities (e.g. multi-physics) to achieve realism in simulations, and to conveniently visualize and explore computed solutions. However, the iterative design process (i.e. the bottom part of Fig 1.) has received little or no attention, and this is unfortunate because the iterative design process, taking engineers from reported results to the next design, helps and inspires engineers devise better engineering designs.
In the current practice, engineers need to perform unproductive and tedious tasks in order to conduct the iterative design process. For example, managing revisions of designs often uses naming conventions applied to computer files generated by CAE software. Such naming conventions are necessary to keep track of exploration of design space. Such practice, however, is prone to user errors. One may accidently overwrite an already conducted analysis, and one may explore a design twice without even being noticed. The lack of support for iterative design processes in CAE software eventually results in reluctance of performing many iterations of design revisions. Insufficient explorations of design space inhabit devising economic and ingenious engineering designs.

In this paper, we first propose essential software requirements for supporting iterative designs in CAE software. These requirements are discussed and implemented in our prototype software incorporating three software components: 1) ESFM – an Essential Software Framework for Meshfree methods[1] for performing mechanical analyses, 2) Qt software framework[2] for creating graphical user interface and generating 2D models to be analyzed, and 3) VTK[3] for visualizing results.

2. SOFTWARE REQUIREMENTS

The main objective of Computer Aided Iterative Design (CAID) software is to extend CAE software to incorporate functionalities for supporting the iterative design process. We propose three essential functionalities in order to support the iterative design process: 1) design-revision tracking, 2) model-revision tracking, and 3) result comparison.

2.1 Design-Revision Tracking

Design-revision tracking concerns about tracking the evolution of designs. It is common that one design may inspire many derivative designs, and many of them may lead to one new design. Keeping the hierarchy of designs helps engineers 1) comprehend the explored design space and 2) strategized exploration plans for the uncharted design space. Such function enables engineers explore the design space effectively and efficiently, and should help devise better designs.

2.2 Model-Revision Tracking

Model-revision tracking refers to tracking changes between the original designs to derivative designs. During the design exploration, existing designs or models are revised to create new designs or models, and these changes should be tracked and recorded, so that engineers can know the difference between the original versus the derivative designs. It is common that differences between two designs cannot be recalled by engineers who created them after an extended period of time. Therefore, keeping these changes would allow engineers quickly understand differences between existing models, leading to comprehension of the explored design space. The changes need to be recorded for model-revision tracking include changes in a) the geometry, b) material property definitions, c) loading conditions, and d) boundary conditions. By recording these changes, engineers can recall the model differences between two related models. Furthermore, in addition to recording these model changes, physical meanings for each change should also be recorded and entered by users. Because Today’s software usually cannot understand physical meanings of add/removing/changing model entities, and these physical meanings may be important to record to make revisions meaningful and self-explained.

2.3 Analysis Results Comparison

The other important function needed to inspire new designs is to be able to compare computed results from different designs, and to be able to work on new designs while displaying the comparison. Users need to be able to compare results from different analyses to see which design performs better. By comparing results from different analyses, new designs can be inspired by comparing results and knowing why one design performs better than the other design in certain aspects.

3. SOFTWARE COMPONENTS

After requirements are identified, prototype software is developed accordingly to realize these requirements, and the prototype software we developed incorporates three
different software libraries: 1) Qt, 2) VTK, and 3) ESFM. These libraries are briefly introduced in this section.

3.1 Qt
Qt [2] is a rich software framework for C++ language. It is available and cross platform on all major operating systems (Windows, MacOS, Linux, etc.). Qt is a rich class library containing many classes, such as graphical user interface (GUI), 2D/3D drawings, networking, database, etc. We mainly use its GUI and 2D drawing classes to develop our prototype software.

3.2 VTK
VTK (Visualization Toolkit [3]) is a high-level graphical class library containing more than 2000 classes, and is available on all major operating systems, just like Qt. VTK uses visualization pipelines to encapsulate low level graphical function calls in OpenGL. Fundamental components in the pipeline, in the usual processing order, contains source \( \rightarrow \) filter \( \rightarrow \) mapper \( \rightarrow \) actor \( \rightarrow \) renderer \( \rightarrow \) render window. Source represents the raw data; filter defines transformations to data; mapper is the procedure to transform data into drawable objects; actor present drawing properties; renderer concretizes the 3D presentation; render window presents the visualization on screen. Table 1 lists the VTK classes used and their purposes.

3.3 ESFM
ESFM (Essential Software Framework for Meshfree Methods [1]) is our homegrown software framework for implementing meshfree methods [4-6]. The software allows us to implement various meshfree methods with different combinations of shape functions, support domain definitions, etc. ESFM is integrated in this work to conduct analyses in solid mechanics.

4. DEMONSTRATION
This section demonstrates some features in our developed prototype program to show how to achieve the functional requirements that we drafted for CAID software.

4.1 Graphical User Interface - Overview
Fig. 2 shows our developed prototype program. The program’s graphical user interface has three windows labeled as A, B, and C in Fig. 2. Window A chooses or creates a design or model to work on; window B presents the modeling space for creating designs; window C is the interface for visualizing analysis results obtained from the analysis for model shown in B. Separating model-selection (A), pre-processing (B), and post-processing (C) into three windows allows the program to take advantage of multiple monitors for presenting information easily. It should be noted the displays in B and C are always synchronized. Furthermore, separating modeling window and post-processing window allows users see the built model with the analyses results simultaneously. Most of today’s CAE software cannot present models with analysis results, and its post-processing windows usually do not present the same detail as in the pre-processing window. Our design removes such restriction and enables better understanding of analysis results with the model.

<table>
<thead>
<tr>
<th>Class</th>
<th>class name</th>
<th>purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>Source</td>
<td>vtkArrowSource</td>
<td>Drawing arrows</td>
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<tr>
<td></td>
<td>vtkConeSource</td>
<td>Drawing cones</td>
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<td>Drawing spheres</td>
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<td>vtkCubeSource</td>
<td>Drawing cubes</td>
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<td>vtkDoubleArray</td>
<td>Data array</td>
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<td></td>
<td>vtkPointData</td>
<td>Point data</td>
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<td></td>
<td>vtkUnstructuredGrid</td>
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<td>vtkDelaunay2D</td>
<td>Delaunay process</td>
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<td></td>
<td>vtkContourFilter</td>
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<td>Mapper</td>
<td>vtkPolyDataMapper</td>
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<td>vtkAxesActor</td>
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<td>vtkColorTransferFunction</td>
<td>Map value to color</td>
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<td>Drawing properties</td>
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<tr>
<td></td>
<td>vtkProperty</td>
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</table>
itemName column can be modified by users to enter meaningful titles for the selected analysis, and more comments can be entered in the bottom part of the window in the “record” tab or the “comment” tab. The check box in front of each model can be used to select models to be compared in the post-processing window. The comparison will be discussed in later sections. The currently active model shown in both pre-processing window and the post-processing window is highlighted with bold font. Each model has also a column recording the date and time of the model creation time automatically generated by the program.

Fig. 2. A three-window design for graphical user interface facilitating the use of multiple monitors

The hierarchy relationships between models are preserved and presented in the model selection window as trees. It is seen in Fig. 3 that models with id 1, 3, and 4 are siblings that are all derived from model with id 0; and the model with id 2 is the child of model id 1. By using trees to manage models, we can easily identify which model is derived from which parent model, and this derivation usually means the child model inherits most of the parent model with some modifications. The modifications of the child model from the parent model will be discussed further in Section 4.4.

4.3 Pre-processing Window
The pre-processing window serves two purposes, one is to create an entirely new model, and the other one is to modify an existing model to create a derived model. It contains functions to 1) drawing geometries, 2) adding forces, 3) imposing boundary conditions, 4) applying material properties, 5) spray calculation nodes, 6) performing modifications, and 7) analyzing. Most functions are rather similar to usual CAE software. However, since the meshfree method is the method of choice in our implementation, nodes need to be spread inside the material domain of interest. There are three ways implemented to spread nodes in a region: 1) use regular spacing, 2) use random spacing, 3) first use regular spacing to generate nodes and then move each spread node by a short random distance. Some methods prefer the third method than the first one. To ensure nodes are spread inside the region of interest, collision detection functions of Qt are used. Each spread node must collide with the interested region in order to be inside of the region, all generated nodes that do not collide with the region will be removed. Thus, using collision detection function Qt eases our implementation of spreading nodes in a specified region.

Fig. 3. The model selection window showing 5 models and their relationships with one another

In addition to creating new models, deriving models from existing designs are common practices. This is achieved by using the model selection window to select an existing model, and then choose “new model” function to create a derived model. Once derived model is created, each modification performed by the user will recorded
automatically in a separate window, as shown in Fig. 5. The window contains all the steps performed (e.g. drawing a line, modify material, etc.) Once an action is logged, users are allowed to comment the logged entry to enter user-specified context for each operation, giving semantic meanings to each operations to help engineers understand these actions for future references.

4.4 Post-processing window

Post-processing or visualizing analysis results are important. They help engineers understand how their models performs under designed conditions, and give them insight on how to improve their designs and inspires new designs. In addition to regular CAE post-processing functions such as contouring, vector plots, etc. We focus on new functions that we introduce in this work in order to support the iterative design process. These functions are mainly used to compare analysis results obtained from different models. There are mainly three functions: 1) simultaneously presenting or more post-processed models (e.g. deformed shapes), 2) showing differences between two analyses by contouring the differences between their field variables, 3) simultaneously query results from selected multiple analyses using bar charts. These are discussed in the subsequent text.

4.4.1 Presenting multiple results simultaneously

Fig. 6 shows the visualization for comparing multiple models with their deformed shapes. The colored presentation is the currently active model, while the outlines are analysis results selected in other analyses. This is not possible with most CAE software today, and engineers usually need to export the data and do such presentation by other tools (e.g. Tecplot) manually. This is tedious, unproductive, and prone to human errors. Such presentation is useful to compare different designs in deformation. Other quantities may require different presentation techniques.

4.4.2 Contouring differences of two analyses

Fig. 6 is only suitable for comparing deformed shapes. However, there are quantities that cannot be compared using outlines, such as stresses and strains. Therefore, in order to understand differences of these quantities on different models, it is necessary to use different approaches than the one previously introduced.

In order to present differences on field variables and how these differences are distributed in space. The function that uses contours to present differences (computed automatically in the software) between two analyses is built in the prototype. Fig. 7 shows such presentation. Such presentation can nicely show not only the magnitude
of differences, but also how the differences are distributed in space. Such functionality does exist in some CAE software, but often they are limited showing differences between steps of the same model. However, there are issues associated with such approach, especially when the two models having different geometries. This is an issue remains to be solved.

Fig. 7 Contouring differences between two analyses.

4.4.3 Comparing quantities from multiple analyses

Finally, sometimes engineers need to compare an important value (e.g. maximum shear stresses calculated) from multiple analyses. Currently, engineers need to manually perform each of the analysis and extract the value from each analysis and then compile collected values in one place in order to compare, and this process is very tedious and hinders engineers to perform more through parametric analyses.

Therefore, our prototype software not only helps manage multiple analyses, it can also collect characteristic values (maximum, minimum, average) of user-specified quantities (shear stress, bending moments, etc.), or quantities at a user-specified point and present these values using bar charts to help them compare the magnitudes of collected quantities, such as the chart in Fig. 8.

5. DISCUSSION

Prototype software with functions to support iterative engineering design is demonstrated in this work. It is our hope that the functions mentioned in this paper will be built into future generation CAE software to help engineers create better designs.

Fig. 8 Comparing results from different analyses

6. ACKNOWLEDGEMENT

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