

Proceedings of the 37th International Symposium on Automation and Robotics in Construction (ISARC 2020)

*From Demonstration to Practical Use
- To New Stage of Construction Robot -*

Kitakyushu, Japan, October 27-28, 2020



37th ISARC 2020 Online



International Association
for Automation and
Robotics in Construction



Knowledge and Competence

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Preface

The 1st International Symposium on Automation and Construction (ISARC) was held at Carnegie Mellon University in Pittsburgh, Pennsylvania, USA in 1984. Since then, ISARC has been held all over the world every year to exchange information about the development and practical use of construction robot technology among industry experts, academic researchers and individuals with novel ideas for all fields of construction, civil and building engineering, machine automation, robotics applications to construction, information technologies, planning, logistics, etc.

ISARC has been held in Japan four times so far, but it has not been held here since 2006, because the momentum for the development of construction robots declined rapidly with the economic downturn around 2000. We were very pleased to learn that we would be able to hold the 37th ISARC in Japan in 2020 after 14 years thanks to the recent increase of momentum in the development of construction robots.

For the symposium, we had planned and prepared to organize not only research presentations, but also key note lectures, technical exhibitions and technical visits related to construction robots in use on the island of Kyushu, in the western part of Japan. Last December, we started a call for papers, and more than 390 abstracts were received from 33 countries.

Unfortunately, the infectious disease caused by COVID-19, which started at the end of last year, quickly spread throughout the world, and many people are still suffering from its effects. We would like to express our heartfelt sympathy to all the people who are in a severe situation, including those who have lost loved ones and/or have been infected by the disease.

There is still no clear end in sight to COVID-19. For this reason, in May of this year, we decided to hold the symposium online and immediately started the preparations for an online symposium. However, we had neither the experience nor the know-how to organize an online international symposium. Therefore, our original plan was not necessarily a very productive one. Under these circumstances, we received tremendous support from the IAARC Board members and were able to hold the online symposium successfully. We would like to extend our sincere gratitude to them for their kindness and great cooperation.

Although the number of submitted papers decreased, due to changes related to an online symposium, we still received 221 full papers from 23 countries. We believe that this symposium was very fruitful in terms of cross-national technical exchange among all the participants.

Finally, I would like to express our deepest gratitude to the members of the Japanese local committee for all the work they did with us in planning and preparing for this symposium. I believe that the efforts of all the people involved in this symposium will greatly contribute to the further evolution of construction robots.

Kazuyoshi Tateyama
Chair, 37th ISARC
Professor, Ritsumeikan University, Japan

Introduction

This publication is the Proceedings of the 37th International Symposium on Automation and Robotics in Construction (ISARC). The symposium was held online during 27-28 October 2020. The Proceedings include an illustrated review of the program, the names of organizations and persons who contributed to the technical program, and the 221 technical papers from 23 countries authored for this international meeting.

The manuscripts were presented during 57 sessions on 3 tracks, among them: automation and robotics, building information modeling (BIM), inspection and monitoring, artificial intelligence and machine learning, construction management, safety and health, data sensing and analysis, mixed Realities (AR/VR), control technology, education, environmental sensing and modeling, human sensing and monitoring, IT supported system, database, big data, lean, logistics, prefabrication, modularization, learning/AI/recognition, human-computer interaction, measurement, modeling and management, new application field of construction robots and machines, risk management, robot and interface design, and robot construction.

Please note: All ISARC proceedings since 1984 are available at no cost at <http://www.iaarc.org>.

We are very grateful for the support of so many. Thank you!

Prof. Kazuyoshi Tateyama, Ritsumeikan University, Japan (Chair)

Prof. Kazuo Ishii, Kyushu Institute of Technology, Japan (Co-Chair)

Prof. Fumihiko Inoue, Shonan Institute of Technology, Japan (Co-Chair)

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Program Schedule

JST*	Tuesday October 27	Wednesday October 28
08:00	Opening Ceremony <i>Tucker-Hasegawa 2020 Award Keynote Lecture</i>	Academic Presentations
– 13:00	Academic Presentations	
14:00 – 15:00	Keynote2	Keynote3
15:00	Academic Presentations	Academic Presentations
– 19:00		Award and Closing Ceremony
20:00 – 23:00	Academic Presentations	

*Japan Standard Time

Keynote

Tucker-Hasegawa 2020 Award Keynote Lecture

Hyoungkwan KIM

Professor at Yonsei University, Korea

Smart Safety Assurance for Temporary Structures

Temporary structures on construction sites has been the major cause of worker fatalities. According to a Korean statistics report, about 300 people are losing precious lives each year due to accidents involving temporary structures. A new research program was launched this year to develop a smart safety assurance system that recognizes, evaluates, and predicts accident risks that may occur during the installation, dismantling, and operation of temporary structures. It is a part of the smart construction initiative sponsored by the Korean Ministry of Land, Infrastructure, and Transport, and the Korea Agency for Infrastructure Technology Advancement. The program was designed for developing technologies such as deep learning-based hazard identification, augmented reality-based risk warning, and smart mobility for intelligent sensing of construction sites, with a total budget of ₩12.5 billion (\$10.5 million) over six years. The program has a clear goal of reducing the number of accidents related to temporary structures by more than 25% through the creation of a new construction culture, safety-related policies, and safety-related industries.

Speaker profile:

Hyoungkwan KIM, Ph.D. is a Professor of the School of Civil and Environmental Engineering at Yonsei University, Korea. His areas of research include construction automation, infrastructure adaptation to climate change, and project finance. He is the principal investigator of a \$10.5 million research program titled “Smart Safety Assurance for Temporary Structures,” which is a part of smart construction initiative sponsored by the Korean Ministry of Land, Infrastructure, and Transport, and the Korea Agency for Infrastructure Technology and Advancement. He serves as Vice- President for the International Association for Automation and Robotics in Construction (IAARC), and Associate Editor for Journal of Computing in Civil Engineering, American Society of Civil Engineers (ASCE). He also served as Secretary General for Association for Engineering Education in Southeast Asia and the Pacific (AESEAP). He has received six excellent teaching awards and an excellent research award from Yonsei University. More information on Prof. Kim can be found at: <http://aim.yonsei.ac.kr>.

Keynote 2

Naoki SATO

Director of the Space Exploration System Technology Unit, The Japan Aerospace Exploration Agency (JAXA), JAXA Space Exploration Center (JSEC), Japan

International Space Exploration and Japanese Lunar Activities

JAXA is engaged in international collaborations to tackle the challenge of human and robotic exploration missions in and beyond low-Earth orbit (LEO). The current focus is exploration missions to the Moon and Mars, targeting future human activities. His presentation introduced Japan's current exploration activities and JAXA's future plans and studies beyond the Earth orbit with the context of international coordination. Especially for the lunar surface activities, the concept study of the lunar base construction, which JAXA had conducted with a group of construction-related companies across Japan, was introduced along with the technological development.

Speaker profile:

Naoki SATO graduated from the Aeronautics Engineering Department, Kyusyu University in 1986, and gained a master degree of applied engineering of Kyusyu University in 1988. In the same year, he entered the National Space Development Agency of Japan (predecessor of JAXA). From 1990 he had been involved in the International Space Station program for about 16 years. Afterwards, he has been working for the international space exploration program formulation. Since April 2018 he is the current ISECG chair and since July 2018 he was assigned as the Director of the Space Exploration System Technology Unit of JAXA Space Exploration Center (JSEC).

Keynote 3

Yasushi NITTA

Director for Construction Equipment and Safety Planning Office, Policy Bureau, Ministry of Land, Infrastructure, Transport and Tourism, Japan

Initiatives for Robot Introduction in Japanese Public Works

The Japanese society faces various social issues such as frequent occurrences of earthquakes, eruption of volcanoes, floods, landslides, etc., resulting in the deterioration of the infrastructure. Japan also sees a reduction of the working population in the construction industry. In his speech, he introduced initiatives for the social implementation of robots and information and communication technologies in the Japanese construction industry, including the Ministry of Land, Infrastructure, Transport and Tourism (MLIT).

Speaker profile:

After graduating from University of Tsukuba in 1994, Dr. Yasushi NITTA joined the Ministry of Land, Infrastructure, Transport and Tourism (MLIT). There he is widely engaged in policy planning, public works and R&D in the various departments, such as MLIT Headquarters, Regional Development Bureau, National Road Office, National Research Institutes (PWRI, NILIM), Advanced Construction Technology Center (ACTEC). He is especially responsible for the planning and operation of on-site verification projects to promote the introduction of robots to the infrastructure department, development/deployment/budgeting/operation of disaster

countermeasure machines, and nationwide deployment of machine construction (i-Construction) using 3D data. Dr. NITTA is also engaged in establishing technical standards for the purpose, demonstrating ultra-long-distance unmanned construction technology, and flood control as an international emergency relief team.

Video list

Construction robots in Japan

1. **Sea Experiment on Tele-operation System of Underwater Excavator**
National Institute of Maritime, Port and Aviation Technology,
Port and Airport Research Institute,
Infrastructure Digital Transformation Engineering Department
2. **Development of Heavy Carrier Robot for Shallow Water Area**
New Unmanned Construction Technology Research Association
3. **Tunnel RemOS-WL**
Kanamoto Co., Ltd.
4. **kana Robo – Robo-Construction System –**
Kanamoto Co., Ltd.
5. **kana Robo – Robo-Construction System 2 –**
Kanamoto Co., Ltd.
6. **ROBO CONSTRUCTION – DokaBOri Training –**
Fujiken Co.,Ltd.
7. **"A4CSEL" at the Seisho Test and Practice Field**
KAJIMA CORPORATION
8. **Pursuing "Zero Ground Subsidence" in Shield Tunneling**
TAC Corporation
9. **Automatic Dam Concrete Placing System**
SHIMIZU CORPORATION
10. **Automatic Tunnel Lining Concrete Placing System**
SHIMIZU CORPORATION
11. **A robot that assists in plotting**
SHIMIZU CORPORATION
12. **Development of IT construction system by Robot**
Public Works Research Institute
13. **Demonstration of autonomous excavation, loading and unmanned bulldozer. (CEATEC2018)**
Komatsu Ltd., Office of CTO
14. **Smart Construction Concept, Future image. (CEATEC2018)**
Komatsu Ltd., Office of CTO
15. **BE A HERO, Future image**
Komatsu Ltd., Office of CTO
16. **DEEP CRAWLER - Crawler type ROV**
WAKACHIKU CONSTRUCTION Co., Ltd.
17. **What is dredging? - A job that protects the safety of the sea**
WAKACHIKU CONSTRUCTION Co., Ltd.
18. **Robotic rubble-mound mechanized construction system**
PENTA-OCEAN CONSTRUCTION CO., LTD.
19. **Rotation Control Device for Lifting Cargo**
WAKACHIKU CONSTRUCTION Co., Ltd.
20. **Automatic operation system of the construction machine (Vibrating roller · Bulldozer)**
HAZAMA ANDO CORPORATION

Table of Contents

Improving Construction Demonstrations by Integrating BIM, UAV, and VR	1
Kun-Chi Wang, Ren-Jie Gao, Sheng-Han Tung and Yuan-Hsiu Chou	
Using Virtual Reality and Augmented Reality for Presale House Customer Change	8
Ben Amed Ouedraogo, Li-Chuan Lien, Unurjargal Dolgorsuren and Yan Ni Liu	
Virtual Prototyping-Based Path Planning of Unmanned Aerial Vehicles for Building Exterior Inspection	16
Zhenjie Zheng, Mi Pan and Wei Pan	
Near Real-Time Monitoring of Construction Progress: Integration of Extended Reality and Kinect V2	24
Ahmed Khairadeen Ali, One Jae Lee and Chansik Park	
VRGlare: A Virtual Reality Lighting Performance Simulator for real-time Three-Dimensional Glare Simulation and Analysis	32
Kieran May, James Walsh, Ross Smith, Ning Gu and Bruce Thomas	
Development of an Augmented Reality Fitness Index for Contractors	40
Hala Nassereddine, Wafik Lotfallah, Awad Hanna and Dharmaraj Veeramani	
A Method to Produce & Visualize Interactive Work Instructions for Modular Products within Onsite Construction	48
Raafat Hussamadin, Jani Mukkavaara and Gustav Jansson	
A Framework for Augmented Reality Assisted Structural Embedment Inspection	56
Jeffrey Kim and Darren Olsen	
Towards Circular Economy in Architecture by Means of Data-driven Design-to- Robotic-Production	63
Ginevra Nazzari and Henriette Bier	
Automated Pavement Marking Defects Detection	67
Andrea Leal Ruiz and Hani Alzraiee	
An Assistive Interface of a Teleoperation System of an Excavator by Overlapping the Predicted Position of the Arm	74
Yuzuki Okawa, Masaru Ito, Ryota Sekizuka, Seiji Saiki, Yoichiro Yamazaki and Yuichi Kurita	
Development of Rotary Snow Blower Vehicle Driving Support System using Quasi-Zenith Satellite on the Expressway in Japan	79
Katsuyoshi Abe, Atsushi Ichikawa, Toshiaki Itou and Keigo Kurihara	
A Systematic Review of the Geographic and Chronological Distributions of 3D Concrete Printers from 1997 to 2020	84
Jihoon Chung, Ghang Lee and Jung-Hoon Kim	

Towards High-Quality Road Construction: Using Autonomous Tandem Rollers for Asphalt Compaction Optimization	90
Jörg Husemann, Patrick Wolf, Axel Vierling, Karsten Berns and Peter Decker	
Ontology-Based Decoding of Risks Encoded in the Prescriptive Requirements in Bridge Design Codes	98
Fahad Ul Hassan and Tuyen Le	
Current Status of Unmanned Construction Technology Developed using a Test Field System	105
Koji Ihara and Takeshi Tamura	
Remote Control Demonstration of the Construction Machine Using 5G Mobile Communication System at Tunnel Construction Site	111
Ken Takai, Hiroaki Aoki, Yusuke Tajima and Michinobu Yoshida	
Sea Experiment on Tele-operation System of Underwater Excavator	118
Tsukasa Kita, Taketsugu Hirabayashi, Atsushi Ueyama, Hiroshi Kinjo, Naoki Oshiro and Nobuyuki Kinjo	
Automation and Operation Record of Large Overhead Crane for Segment Transportation	126
Yasushi Nishizaki, Koki Takahashi, and Takashi Fukui	
Development of an Automated Angle Control System to Improve Safety and Productivity	134
Tsuyoshi Fukuda, Takumi Arai, Kousuke Kakimi and Keishi Matsumoto	
Automated Detection for Road Marking Quality, using Visual Based Machine Learning	139
Firas Habbal, Fawaz Habbal, Abdualla Alnuaimi, Shafia Alkheyaili and Ammar Safi	
A Construction Progress On-site Monitoring and Presentation System Based on The Integration of Augmented Reality and BIM	147
Sheng-Kai Wang and Hung-Ming Chen	
Rule-Based Generation of Assembly Sequences for Simulation in Large-Scale Plant Construction ·	155
Jan Weber, Jana Stolipin, Ulrich Jessen, Markus König and Sigrid Wenzel	
An analysis of 4D-BIM Construction Planning: Advantages, Risks and Challenges	163
Pedram Farnood Ahmadi and Mehrdad Arashpour	
Ontology-based Product Configuration for Modular Buildings	171
Jianpeng Cao and Daniel Hall	
On construction-specific Product Structure Design and Development: the BIM Enhancement Approach	177
Solmaz Mansoori, Harri Haapasalo and Janne Härkönen	
Parametric Structural Design for automated Multi-Objective Optimization of Flexible Industrial Buildings	185
Julia Reisinger, Maximilian Knoll and Iva Kovacic	

Inspection of Discrepancies in Construction Temporary Safety Structures through Augmented Reality	193
Hashim Raza Bokhari, Doyeop Lee, Numan Khan and Chansik Park	
Status of 4D BIM Implementation in Indian Construction	199
V. Paul C. Charlesraj and Talapaneni Dinesh	
An Information Quality Assessment Framework for Developing Building Information Models	207
Liji Chen and Justin K. W. Yeoh	
BIM Based Information Delivery Controlling System	215
Brian Klusmann, Zhiwei Meng, Noemi Kremer, Anica Meins-Becker and Manfred Helmus	
Development of an Open-source Scan+BIM Platform	223
Enrique Valero, Dibya D. Mohanty and Frederic Bosche	
BuiltView: Integrating LiDAR and BIM for Real-Time Quality Control of Construction Projects	233
Rana Abbas, F. A. Westling, Christian Skinner, Monica Hanus-Smith, Andrew Harris and Nathan Kirchner	
Single Shared Model Approach for Building Information Modelling	240
Simo Ruokamo and Heikkila Rauno	
Parametric or Non-parametric? Understanding the Inherent Trade-offs between Forms of Object Representation	248
Christopher Rausch, Yinghui Zhao and Carl Haas	
Development of a Twin Model for Real-time Detection of Fall Hazards	256
Leonardo Messi, Alessandra Corneli, Massimo Vaccarini and Alessandro Carbonari	
Automatized Parametric Modeling to Enhance a data-based Maintenance Process for Infrastructure Buildings	264
Robert Hartung, Robin Schönbach, Dominic Liepe and Katharina Klemt-Albert	
Gamification and BIM Teaching the BIM Method through a Gamified, Collaborative Approach	272
Carla Pütz, Christian Heins, Manfred Helmus and Anica Meins-Becker	
Opportunities and Challenges of Digital Twin Applications in Modular Integrated Construction	278
Mingcheng Xie and Wei Pan	
Integrating Industry 4.0 Associated Technologies into Automated and Traditional Construction	285
Fabiano Correa	
System Development of an Augmented Reality On-site BIM Viewer Based on the Integration of SLAM and BLE Indoor Positioning	293
Yu-Cheng Liu, Jhih-Rong Chen and Hung-Ming Chen	
Review of Construction Workspace Definition and Case Studies	301
Kuan-Fan Lai and Ying-Chieh Chan	

A Web-Based Approach to Dynamically Assessing Space Conflicts by Integrating BIM and Graph Database	307
Wei-Ting Chien and Shang-Hsien Hsieh	
Deployment of a Standardized BIM Modeling Guideline for the Planning and Construction Industry	313
Gamze Hort, Daiki John Feller, Anica Meins-Becker and Manfred Helmus	
Design for Digital Fabrication: an Industry needs Analysis of Collaboration Platforms and Integrated Management Processes	318
Ming Shan Ng, Marcella M. Bonanomi, Daniel M. Hall and Jürgen Hackl	
A BIM-Based Approach for Optimizing HVAC Design and Air Distribution System Layouts in Panelized Houses	326
Pouya Baradaran-Noveiri, Mohammed Zaheeruddin and Sang Hyeok Han	
Synthetic Data Generation for Indoor Scene Understanding Using BIM	334
Yeji Hong, Somin Park and Hyoungkwan Kim	
Cyber-physical System for Diagnosing and Predicting Technical Condition of Servo-drives of Mechatronic Sliding Complex during Construction of High-rise Monolithic Buildings	339
Alexey Bulgakov, Thomas Bock and Tatiana Kruglova	
Proposal for Automation System Diagram and Automation Levels for Earthmoving Machinery	347
Takeshi Hashimoto, Mitsuru Yamada, Genki Yamauchi, Yasushi Nitta and Shinichi Yuta	
Applications of LiDAR for Productivity Improvement on Construction Projects: Case Studies from Active Sites	353
Fredrik Westling, Rana Abbas, Christian Skinner, Monica Hanus-Smith, Andrew Harris and Nathan Kirchner	
Design and Construction of Shell-shaped Bench using a 3D Printer for Construction	362
Hajime Sakagami, Haruna Okawa, Masaya Nakamura, Takuya Anabuki, Yoshikazu Ishizeki and Tomoya Kaneko	
Requirements for Safe Operation and Facility Maintenance of Construction Robots	369
Alexey Bulgakov, Thomas Bock, Jens Otto, Natalia Buzalo and Thomas Linner	
Safety Concept and Architecture for Autonomous Haulage System in Mining	377
Hidefumi Ishimoto and Tomoyuki Hamada	
On-site Autonomous Construction Robots: A review of Research Areas, Technologies, and Suggestions for Advancement	385
Xinghui Xu and Borja Garcia de Soto	
Curtain Wall Installation for High-Rise Buildings: Critical Review of Current Automation Solutions and Opportunities	393
Brandon Johns, Mehrdad Arashpour and Elahe Abdi	
Rationalization of Free-form Surface Construction Method using Wooden Formwork	401
Sei Hayashi and Tomoyuki Gondo	

Comparison of Shortest Path Finding Algorithms for Cable Networks on Industrial Construction Projects	409
Fatima Alsakka, Salam Khalife, Maram Nomir, Yasser Mohamed and Rick Hermann	
Constructability: The Prime Target in Value Engineering for Design Optimization	417
Arun Sekhar and Uma Maheswari	
Blockchain based Framework for Verifying the Adequacy of Scaffolding Installation	425
Chanwoo Baek, Doyeop Lee and Chansik Park	
Towards a Comprehensive Facade Inspection Process: An NLP based Analysis of Historical Facade Inspection Reports for Knowledge Discovery	433
Zhuoya Shi, Keundeok Park and Semiha Ergan	
Scheduling Simulator by Ensemble Forecasting of Construction Duration	441
Shigeomi Nishigaki, Katsutoshi Saibara, Takashi Ootsuki and Hirokuni Morikawa	
A Technology Platform for a Successful Implementation of Integrated Project Delivery for Medium Size Projects	449
Luke Psomas and Hani Alzraiee	
Simulation-based Reinforcement Learning Approach towards Construction Machine Automation ..	457
Keita Matsumoto, Atsushi Yamaguchi, Takahiro Oka, Masahiro Yasumoto, Satoru Hara, Michitaka Iida and Marek Teichmann	
Optimization of Trajectories for Cable Robots on Automated Construction Sites	465
Roland Boumann, Patrik Lemmen, Robin Heidel and Tobias Bruckmann	
A Robust Framework for Identifying Automated Construction Operations	473
Aparna Harichandran, Benny Raphael and Abhijit Mukherjee	
Analysis of Excavation Methods for a Small-scale Mining Robot	481
Michael Berner and Nikolaus August Sifferlinger	
Robotic Insertion of Timber Joints using Visual Detection of Fiducial Markers	491
Nicolas Rogeau, Victor Tiberghien, Pierre Latteur and Yves Weinand	
Constraint Control of a Boom Crane System	499
Michele Ambrosino, Arnaud Dawans and Emanuele Garone	
Optimal Travel Routes of On-road Vehicles Considering Sustainability	507
Nassim Mehrvarz, Zhilin Ye, Khalegh Barati and Xuesong Shen	
Modeling and Control of 5-DoF Boom Crane	514
Michele Ambrosino, Marc Berneman, Gianluca Carbone, Rémi Crépin, Arnaud Dawans and Emanuele Garone	
Automating Crane Lift Path through Integration of BIM and Path Finding Algorithm	522
Songbo Hu and Yihai Fang	

A study on an Autonomous Crawler Carrier System with AI based Transportation Control	530
Hironobu Hatamoto, Kazuya Fujimoto, Tsubasa Asuma, Yoshito Takeshita, Tetsuo Amagai, Atsushi Furukawa and Shigeo Kitahara	
Accuracy and Generality of Trained Models for Lift Planning Using Deep Reinforcement Learning - Optimization of the Crane Hook Movement Between Two Points -	538
Aoi Tarutani and Kosei Ishida	
Reaching Difficulty Model of Swinging Operations of a Hydraulic Excavator Considering the First-Order Delay	547
Kazuyuki Matsumura, Masaru Ito, Chiaki Raima, Seiji Saiki, Yoichiro Yamazaki and Yuichi Kurita	
Mechatronic Control System for Leveling of Bulldozer Blade	552
Alexey Bulgakov, Thomas Bock and Georgii Tokmakov	
Multiple Tower Crane Selection methodology utilizing Genetic Algorithm	558
Preet Lodaya, Abhishek Raj Singh and Venkata Santosh Kumar Delhi	
Fuzzy Controller Algorithm for Automated HVAC Control	566
Myungjin Chae, Kyubyung Kang, Dan D. Koo, Sukjoon Oh and Jae Youl Chun	
A Probabilistic Motion Control Approach for Teleoperated Construction Machinery	571
Hyung Joo Lee and Sigrid Brell-Cokcan	
Excavation Path Generation for Autonomous Excavator Considering Bulking Factor of Soil	578
Shinya Katsuma, Ryosuke Yajima, Shunsuke Hamasaki, Pang-Jo Chun, Keiji Nagatani, Genki Yamauchi, Takeshi Hashimoto, Atsushi Yamashita and Hajime Asama	
Development of an Algorithm for Crane Sway Suppression	584
Yasuhiro Yamamoto, Chunnan Wu, Hisashi Osumi, Masayuki Yano and Yusuke Hara	
Analysis of Energy Efficiency of a Backhoe during Digging Operation	589
Yusuke Sano, Chunnan Wu, Hisashi Osumi, Yuki Kawashima and Tomoaki Tsuda	
Action Recognition of Construction Machinery from Simulated Training Data Using Video Filters ..	595
Jinhyeok Sim, Jun Younes Louhi Kasahara, Shota Chikushi, Hiroshi Yamakawa, Yusuke Tamura, Keiji Nagatani, Takumi Chiba, Shingo Yamamoto, Kazuhiro Chayama, Atsushi Yamashita and Hajime Asama	
Real-time Early Warning of Clogging Risk in Slurry Shield Tunneling: A Self-updating Machine Learning Approach	600
Qiang Wang, Xiongyao Xie and Yu Huang	
Efficient Numerical Methods for Accurate Modeling of Soil Cutting Operations	608
Amin Haeri, Dominique Tremblay, Krzysztof Skonieczny, Daniel Holz and Marek Teichmann	
IoT-enabled Dependable Co-located Low-cost Sensing for Construction Site Monitoring	616
Huyhn A. D. Nguyen, Lanh V. Nguyen and Quang P. Ha	

Threat Modeling in Construction: An Example of a 3D Concrete Printing System	625
Maahir Ur Rahman Mohamed Shibly and Borja Garcia de Soto	
Measuring Adhesion Strength of Wall Tile to Concrete by Non-Contact Inspection Using Electromagnetic Waves	633
Hussain Alsalem, Takayuki Tanaka, Takumi Honda, Satoru Doi and Shigeru Uchida	
Construction Method of Super Flat Concrete Slab using High Precision Height Measurement	639
Yutaro Fukase, Ryosuke Saito, Yoshiaki Takemoto and Yoshiki Muramatsu	
Method for Estimating Subgrade Reaction Modulus by Measuring Wheel-terrain Interactions	646
Yasushi Wada and Taizo Kobayashi	
Report on the Measurement of the Form of SHOTCRETE GRID BEAM-FREE FRAME Using Point Cloud Data	650
Kojima Takayuki and Yori Nomoto	
Single Camera Worker Detection, Tracking and Action Recognition in Construction Site	653
Hiroaki Ishioka, Xinshuo Weng, Yunze Man and Kris Kitani	
MR-based Equipment Remote Control and 3D Digital Working Guidance for Field-oriented Maintenance	661
Jinwoo Song, Kyuhyup Lee, Minkyong Jeong, Sejoon Lee and Soonwook Kwon	
Use of Laser scanning, Remote Sensors & Traffic Data Collection, Drones & Mobile Application. MoEI Federal Highways network case study.	669
Khamis Al Sheyahi, Habiba Noor Aflatoon and Daniel Llort Mac Donald	
Safety Monitoring of Construction Equipment based on Multi-sensor Technology	677
Ziqing Yang, Jian Yang and Enliu Yuan	
Autonomous UAV flight using the Total Station Navigation System in Non-GNSS Environments	685
Akira Ishii, Takato Yasuno, Masazumi Amakata, Hiroaki Sugawara, Junichiro Fujii and Kohei Ozasa	
Depth-Camera-Based In-line Evaluation of Surface Geometry and Material Classification For Robotic Spraying	693
Valens Frangez, David Salido-Monzú and Andreas Wieser	
Combining Reality Capture and Augmented Reality to Visualise Subsurface Utilities in the Field	703
Lasse Hedegaard Hansen, Simon Swanström Wyke and Erik Kjems	
Condition Prediction of Highway Assets Based on Spatial Proximity and Interrelations of Asset Classes: A Case Study	711
Arash Karimzadeh, Sepehr Sabeti, Hamed Tabkhib and Omidreza Shoghli	
A Simulation Approach to Optimize Concrete Delivery using UAV Photogrammetry and Traffic Data	719
Robert Sprotte and Hani Alzraiee	

Quality Control for Concrete Steel Embed Plates using LiDAR and Point Cloud Mapping	727
Hani Alzraiee, Robert Sprotte and Andrea Leal Ruiz	
Exploring Gerontechnology for Aging-Related Diseases in Design Education: An Interdisciplinary Perspective	735
Rongbo Hu, Thomas Linner, Marc Schmitz, Jörg Güttler, Yuan Lu and Thomas Bock	
Changing Paradigm: a Pedagogical Method of Robotic Tectonics into Architectural Curriculum	743
Xinyu Shi, Xue Fang, Zhoufan Chen, Tyson Keen Phillips and Hiroatsu Fukuda	
Augmented Reality Sandboxes for Civil and Construction Engineering Education	750
Joseph Louis and Jennifer Lather	
Education of Open Infra BIM based Automation and Robotics	757
Kolli Tanja and Heikkila Rauno	
Automated Data Acquisition for Indoor Localization and Tracking of Materials Onsite	765
Hassan Bardareh and Osama Moselhi	
Laser Scanning with Industrial Robot Arm for Raw-wood Fabrication	773
Petras Vestartas and Yves Weinand	
Workspace Modeling: Visualization and Pose Estimation of Teleoperated Construction Equipment from Point Clouds	781
Jing Dao Chen, Pileun Kim, Dong-Ik Sun, Chang-Soo Han, Yong Han Ahn, Jun Ueda and Yong Cho	
A Critical Review of Machine Vision Applications in Construction	789
Saeed Ansari Rad and Mehrdad Arashpour	
An Agent-based Approach for Modeling Human-robot Collaboration in Bricklaying	797
Ming-Hui Wu and Jia-Rui Lin	
A Vision for Evaluations of Responsive Environments in Future Medical Facilities	805
Daniel Lu, Semiha Ergan, Devin Mann and Katharine Lawrence	
Toolbox Spotter: A Computer Vision System for Real World Situational Awareness in Heavy Industries	813
Stuart Eiffert, Alex Wendel, Peter Colborne-Veel, Nicholas Leong, John Gardenier and Nathan Kirchner	
Evaluating SLAM 2D and 3D Mappings of Indoor Structures	821
Yoshihiro Nitta, Derbew Yenet Bogale, Yorimasa Kuba and Zhang Tian	
A Novel Audio-Based Machine Learning Model for Automated Detection of Collision Hazards at Construction Sites	829
Khang Dang and Tuyen Le	
Training of YOLO Neural Network for the Detection of Fire Emergency Assets	836
Alessandra Corneli, Berardo Naticchia, Massimo Vaccarini , Frederic Bosché and Alessandro Carbonari	

Improvement of 3D Modeling Efficiency and Accuracy of Earthwork Site by Noise Processing Using Deep Learning and Structure from Motion	844
Nobuyoshi Yabuki, Yukako Sakamoto and Tomohiro Fukuda	
Real-time Judgment of Workload using Heart Rate and Physical Activity	849
Nobuki Hashiguchi, Lim Yeongjoo, Cyo Sya, Shinichi Kuroishi, Yasuhiro Miyazaki, Shigeo Kitahara, Taizo Kobayashi, Kazuyoshi Tateyama and Kota Kodama	
An Integrated Sensor Network Method for Safety Management of Construction Workers	857
Tingsong Chen, Nobuyoshi Yabuki and Tomohiro Fukuda	
Data-Driven Worker Detection from Load-View Crane Camera	864
Tanittha Sutjaritvorakul, Axel Vierling and Karsten Berns	
Using Deep Learning for Assessment of Workers' Stress and Overload	872
Sahel Eskandar and Saiedeh Razavi	
Development of a Workers' Behavior Estimation System Using Sensing Data and Machine Learning	878
Rikuto Tanaka, Nobuyoshi Yabuki and Tomohiro Fukuda	
Incident Detection at Construction Sites via Heart-Rate and EMG Signal of Facial Muscle	886
Mizuki Sugimoto, Shunsuke Hamasaki, Ryosuke Yajima, Hiroshi Yamakawa, Kaoru Takakusaki, Keiji Nagatani, Atsushi Yamashita and Hajime Asama	
Scenario-Based Construction Safety Training Platform Using Virtual Reality	892
Ankit Gupta and Koshy Varghese	
Generation of Orthomosaic Model for Construction Site using Unmanned Aerial Vehicle	900
Alexey Bulgakov, Daher Sayfeddine, Thomas Bock and Awny Fares	
Field Application of Tunnel Half Section Inspection System	905
Nobukazu Kamimura, Satoru Nakamura, Daisuke Inoue and Takao Ueno	
Challenges in Capturing and Processing UAV based Photographic Data From Construction Sites ..	911
Saurabh Gupta and Syam Nair	
Research and Development on Inspection Technology for Safety Verification of Small-Scale Bridges using Three-Dimensional Model	919
Kazuhiko Seki, Koichi Iwasa, Satoshi Kubota, Yoshinori Tsukada, Yoshihiro Yasumuro and Ryuichi Imai	
Development of Cloud Computing System for Concrete Structure Inspection by Deep Learning Based Infrared Thermography Method	927
Shogo Hayashi, Koichi Kawanishi, Isao Ujike and Pang-Jo Chun	
Stereo Vision based Hazardous Area Detection for Construction Worker's Safety	935
Doyeop Lee, Numan Khan and Chansik Park	

Artificial Intelligence and Blockchain-based Inspection Data Recording System for Portable Firefighting Equipment	941
Numan Khan, Doyeop Lee, Ahmed Khairadeen Ali and Chansik Park	
Development of Field View Monitor 2 -An assisting function for safety check around a hydraulic excavator using real-time image recognition with monocular cameras-	948
Yoshihisa Kiyota, Shunsuke Otsuki, Susumu Aizawa and Danting Li	
Development of ROV for visual inspection of Concrete Pier Superstructure	954
Toshinari Tanaka, Shuji Nogami, Ema Kato and Tsukasa Kita	
An automated Approach to Digitise Railway Bridges	962
Mustafa Al-Adhami, Sagal Rooble, Song Wu, Clara Osuna-Yevenes, Veronica Ruby-Lewis, Mark. Greatrix, Yreilyn Cartagena and Saeed Talebi	
Mirror-aided Approach for Surface Flatness Inspection using Laser Scanning	969
Fangxin Li and Min-Koo Kim	
A Predictive Model for Scaffolding Man-hours in Heavy Industrial Construction Projects	976
Wenjing Chu, Sanghyeok Han, Zhen Lei, Ulrich Hermann and Di Hu	
Ontological Base for Concrete Bridge Rehabilitation Projects	984
Chengke Wu, Rui Jiang, Jun Wang, Jizhuo Huang and Xiangyu Wang	
IoT Enabled Framework for Real-time Management of Power-Tools at Construction Projects	992
Ashish Kumar Saxena, Varun Kumar Reja and Koshy Varghese	
Web-Based Communication Platform for Decision Making in Early Design Phases	1000
Zhiwei Meng, Ata Zahedi and Frank Petzold	
Decision Support System for Site Layout Planning	1008
Abhishek Raj Singh, Ankan Karmakar and Venkata Santosh Kumar Delhi	
Factors Affecting the Implementation of AI-based Hearing Protection Technology at Construction Workplace	1014
Yongcan Huang and Tuyen Le	
Project Work Breakdown Structure Similarity Estimation Using Semantic and Structural Similarity Measures	1021
Navid Torkanfar and Ehsan Rezazadeh Azar	
ABM and GIS Integration for Investigating the Influential Factors Affecting Wildfire Evacuation Performance	1029
Qi Sun and Yelda Turkan	
Streamlining Photogrammetry-based 3D Modeling of Construction Sites using a Smartphone, Cloud Service and Best-view Guidance	1037
Ryota Moritani, Satoshi Kanai, Kei Akutsu, Kiyotaka Suda, Abdalrahman Elshafey, Nao Urushidate and Mitsuru Nishikawa	

Cyber Agent to Support Workers' Decision Making for Mechanized Earthwork	1045
Shigeomi Nishigaki, Katsutoshi Saibara, Takashi Otsuki and Hirokuni Morikawa	
Research on Standardization of Construction Site Time-series Change Information as Learning Data for Automatic Generation of Work Plan of Construction Machinery in Earthworks	1053
Takashi Otsuki, Hirokuni Morikawa, Yushi Shiiba, Seigo Ogata and Masaharu Moteki	
Energy Performance and LCA-driven Computational Design Methodology for Integrating Modular Construction in Adaptation of Concrete Residential Towers in Cold Climates	1061
Sheida Shahi, Patryk Wozniczka, Tristan Truysenb, Ian Trudeau and Carl Haas	
A View of Construction Science and Robot Technology Implementation	1069
Hiroshi Yamamoto	
Constructible Design for Off-site Prefabricated Structures in Industrial Environments: Review of Mixed Reality Applications	1074
Ankit Shringi, Mehrdad Arashpour and Arnaud Prouzeau	
Financial Modeling for Modular and Offsite Construction	1082
Tarek Salama, Gareth Figgess, Mohamed Elsharawy and Hossam Elsokkary	
A Novel Methodological Framework of Smart Project Delivery of Modular Integrated Construction	1090
Wei Pan, Mi Pan and Zhenjie Zheng	
Block Chain based Remicon Quality Management	1098
Seungwon Cho, Doyeop Lee and Chansik Park	
A Conceptual Model for Transformation of Bill of Materials from Offsite Manufacturing to Onsite Construction in Industrialized House-building	1106
Raafat Hussamadin, Mikael Viklund Tallgren and Gustav Jansson	
Study on the Level Concept of Autonomous Construction in Mechanized Construction	1114
Hirokuni Morikawa and Takashi Otsuki	
Mask R-CNN Deep Learning-based Approach to Detect Construction Machinery on Jobsites	1122
Hamed Raoofi and Ali Motamedi	
Implementation of Unsupervised Learning Method in Rule Learning from Construction Schedules	1128
Boong Yeol Ryoo and Milad Ashtab	
Evaluation of Spalling in Bridges Using Machine Vision Method	1136
Eslam Mohammed Abdlekader, Osama Moselhi, Mohamed Marzouk and Tarek Zayed	
Improving Construction Project Schedules before Execution	1144
John Fitzsimmons, Ying Hong and Ioannis Brilakis	
Automated On-Site Quality Inspection and Reporting Technology for Off-Site Construction (OSC)-based Precast Concrete Members	1152
Seojoon Lee, Soonwook Kwon, Minkyong Jeong, Syedmobeen Hasan and Alexander Kim	

The Impact of Integrating Augmented Reality into the Production Strategy Process	1160
Hala Nassereddine, Dharmaraj Veeramani and Awad Hanna	
Automatic Detection of Air Bubbles with Deep Learning	1168
Takuma Nakabayashi, Koji Wada and Yoshikazu Utsumi	
Using a Virtual Reality-based Experiment Environment to Examine Risk Habituation in Construction Safety	1176
Namgyun Kim and Changbum Ryan Ahn	
Towards a Computational Approach to Quantify Human Experience in Urban Design: A Data Collection Platform	1183
Keundeok Park and Semiha Ergan	
Investigation of Changes in Eye-Blink Rate by VR Experiment for Incident Detection at Construction Sites	1191
Shunsuke Hamasaki, Mizuki Sugimoto, Ryosuke Yajima, Atsushi Yamashita, Keiji Nagatani and Hajime Asama	
BIM-Aided Scanning Path Planning for Autonomous Surveillance UAVs with LiDAR	1195
Changhao Song, Kai Wang and Jack C. P. Cheng	
Research on a Method to Consider Inspection and Processing for Atypical Wood Members Using 3D Laser Scanning	1203
Shunsuke Someya, Yasushi Ikeda, Kensuke Hotta, Seigo Tanaka, Mizuki Hayashi, Mitsuhiro Jokaku and Taito Takahashi	
Generative Damage Learning for Concrete Aging Detection using Auto-flight Images	1211
Takato Yasuno, Akira Ishii, Junichiro Fujii, Masazumi Amakata and Yuta Takahashi	
Evaluation of Drainage Gradient using Three-dimensional Measurement Data and Physics Engine	1219
Kosei Ishida	
Stakeholder Perspectives on the Adoption of Drones in Construction Projects	1227
V. Paul C. Charlesraj and Nijalingamurthy Rakshith	
Examination of Efficiency of Bridge Periodic Inspection Using 3D Data (Point Cloud Data and Images)	1235
Tatsuru Ninomiya, Mami Enomoto, Mitsuharu Shimokawa, Tatsuya Hattori and Yasushi Nitta	
Experimental Result of Third-person View Generation using Deliberately Delayed Omni-directional Video	1240
Akira Sakata, Yasushi Hada, Rei Hojo, Masahiro Munemoto, Yoshito Takeshita, Tsubasa Asuma and Shigeo Kitahara	
Construction Operation Assessment and Correction Using Laser Scanning and Projection Feedback	1247
Alexei Pevzner, Saed Hasan, Rafael Sacks and Amir Degani	

OpenBridgeGraph: Integrating Open Government Data for Bridge Management	1255
Jia-Rui Lin	
Five-dimensional Simulation of Bridge Engineering Based on BIM and VR	1263
Kun-Chi Wang, Sheng-Han Tung, Wei-Chih Chen and Zi-Chi Zhao	
Digital Twinning of Railway Overhead Line Equipment from Airborne LiDAR Data	1270
M. R. Mahendrini Fernando Ariyachandra and Ioannis Brilakis	
A Shared Ontology for Logistics Information Management in the Construction Industry	1278
Yuan Zheng, Müge Tetik, Seppo Törmä, Antti Peltokorpi and Olli Seppänen	
Visualization of the Progress Management of Earthwork Volume at Construction Jobsite	1286
Hajime Honda, Akifumi Minami, Yoshihiko Takahashi, Seishi Tajima, Takashi Ohtsuki and Yushi Shiiba	
Incentivizing High-Quality Data Sets in Construction Using Blockchain: A Feasibility Study in the Swiss Industry	1291
Jens J. Hunhevicz, Tobias Schraner and Daniel M. Hall	
A Holistic Framework for the Implementation of Big Data throughout a Construction Project Lifecycle	1299
Makram Bou Hatoum, Melanie Piskernik and Hala Nassereddine	
Automatic Analysis of Idling in Excavator's Operations Based on Excavator-Truck Relationships ..	1307
Chen Chen, Zhenhua Zhu and Amin Hammad	
Construction 4.0: A Roadmap to Shaping the Future of Construction	1314
Mahmoud El Jazzar, Harald Urban, Christian Schranz, and Hala Nassereddine	
Deep Learning-based Question Answering System for Proactive Disaster Management	1322
Yohan Kim, Jiu Sohn, Seongdeok Bang and Hyoungkwan Kim	
Overall Utilization of Information and Communication Technologies in Excavation Work and Management at Yoneshiro-gawa River, A First-class River	1327
Tatsuro Masu, Akihiro Ishii, Fumihiko Tamori, Hanako Hatakeyama, Yutaka Suzuki, Satoshi Shirato and Yurie Abe	
Weakly Supervised Defect Detection using Acoustic Data based on Positive and Negative Constraints	1331
Jun Younes Louhi Kasahara, Atsushi Yamashita and Hajime Asama	
Road Maintenance Management System Using 3D Data by Terrestrial Laser Scanner and UAV	1337
Satoshi Kubota, Ryosuke Hata, Kotaro Nishi, Chiyuan Ho and Yoshihiro Yasumuro	
Traffic Regulation Technology by Movable Barriers	1344
Toshiharu Tanikawa and Tohya Okishio	
Development and Verification of Inspection Method for Concrete Surface utilizing Digital Camera ..	1351
Shungo Matsui, Yoshimasa Nakata, Hidenori Shitashimizu, Ryota Nakatsuji, Takeshi Ueda and Naoiki Maehara	

MLIT's Initiatives for Promotion the Efficient Construction and Inspection by using new Technologies such as AI and Robots in Japan.	1356
Kenichi Watanabe	
Track Similarity-based Typhoon Search Engine for Disaster Preparedness	1361
Chun-Mo Hsieh, Cheng-Yu Ho, Hung-Kai Kung, Hao-Yung Chan, Meng-Han Tsai and Yun-Cheng Tsai	
Cracks Detection using Artificial Intelligence to Enhance Inspection Efficiency and Analyze the Critical Defects	1367
Fawaz Habbal, Abdulla Alnuaimi, Mohammed Al Shamsi, Saleh Alshaibah and Thuraya Aldarmaki Thuraya.Aldarmaki	
Smart Tunnel Inspection and Assessment using Mobile Inspection Vehicle, Non-Contact Radar and AI	1373
Toru Yasuda, Hideki Yamamoto, Mami Enomoto and Yasushi Nitta	
Applications of Building Information Modeling (BIM) in Disaster Resilience: Present Status and Future Trends	1380
Sadegh Khanmohammadi, Mehrdad Arashpour and Yu Bai	
Integrating BIM- and Cost-included Information Container with Blockchain for Construction Automated Payment using Billing Model and Smart Contracts	1388
Xuling Ye, Katharina Sigalov and Markus König	
An Agent-based Framework for Evaluating Location-based Risk Score in Indoor Emergency Evacuation	1396
Tianlun Cai, Jiamou Liu, Hong Zheng, Yupan Wang and Vicente Gonzalez	
A Framework for Camera Planning in Construction Site using 4D BIM and VPL	1404
Si Tran, Ahmed Khairadeen Ali, Numan Khan, Doyeop Lee and Chansik Park	
Safe and Lean Location-based Construction Scheduling	1409
Beidi Li, Carl Schultz, Jürgen Melzner, Olga Golovina, and Jochen Teizer	
Don't Risk Your Real Estate Actions to Realize Efficient Project Risk Management using the BIM Method	1417
Maike Eilers, Carla Pütz, Manfred Helmus and Anica Meins-Becker	
Introduction of the New Safety Concept "Safety2.0" to Reduce the Risk of Machinery Accidents ...	1424
Hidesato Kojima, Takaya Fujii, Yasushi Mihara and Hiroaki Ihara	
Applying ANN to the AI Utilization in Forecasting Planning Risks in Construction	1431
Fawaz Habbal, Firas Habbal, Abdulla Alnuaimi, Anwar Alshimmari, Nawal Alhanaee and Ammar Safi	
Development of A Mobile Robot pulling An Omni-directional Cart for A Construction Site	1438
Yusuke Takahashi, Yoshiro Hada and Satoru Nakamura	
Developing a Windshield Display for Mobile Cranes	1444
Taufik Akbar Sitompul, Simon Roysson and José Rosa	

Development of Simple Attachment for Remote Control (DokaTouch)	1452
Kazuki Sumi	
Preliminary Development of a Powerful and Backdrivable Robot Gripper Using Magnetorheological Fluid	1458
Sahil Shembekar, Mitsuhiro Kamezaki, Peizhi Zhang, Zhouyi He, Tsunoda Ryuichiro, Hiroyuki Sakamoto and Shigeki Sugano	
Development and Application of a Fire Resistive Covering Spraying Robot to Building Construction Site	1464
Yuichi Ikeda, Hirofumi Segawa and Nobuyoshi Yabuki	
A Cable Driven Parallel Robot with a Modular End Effector for the Installation of Curtain Wall Modules	1472
Kepa Iturralde, Malte Feucht, Rongbo Hu, Wen Pan, Marcel Schlandt, Thomas Linner, Thomas Bock, Jean-Baptiste Izard, Ibon Eskudero, Mariola Rodriguez, Jose Gorrotxategi, Julen Astudillo, Joao Cavalcanti, Marc Gouttefarde, Marc Fabritius, Christoph Martin, Tomas Henninge, Stein M. Nornes, Yngve Jacobsen, A. Pracucci, Jesús Cañada, José David Jimenez-Vicaria, Carlo Paulotto, Ruben Alonso and Lorenzo Elia	
Bi-Directional Communication Bridge for State Synchronization between Digital Twin Simulations and Physical Construction Robots	1480
Ci-Jyun Liang, Wes McGee, Carol Menassa and Vineet Kamat	
Parallel Kinematic Construction Robot for AEC Industry	1488
Maike Klöckner, Mathias Haage, Klas Nilsson, Anders Robertsson and Ronny Andersson	
Design-to-Robotic-Production and -Assembly for Architectural Hybrid Structures	1496
Henriette Bier, Arwin Hidding and Marco Galli	
Design and Synthesis of the Localization System for the On-site Construction Robot	1501
Wen Pan, Rui Li and Thomas Bock	
Online Synchronization of Building Model for On-Site Mobile Robotic Construction	1508
Selen Ercan Jenny, Hermann Blum, Abel Gawel, Roland Siegwart, Fabio Gramazio and Matthias Kohler	
A Methodology to Monitor Construction Progress Using Autonomous Robots	1515
Samuel A. Prieto, Borja Garcia de Soto and Antonio Adan	
Digital Twin Technology Utilizing Robots and Deep Learning	1523
Fuminori Yamasaki	
Real-Time Process-Level Digital Twin for Collaborative Human-Robot Construction Work	1528
Xi Wang, Ci-Jyun Liang, Carol Menassa and Vineet Kamat	
Research and Development of Construction Technology in Social Cooperation Program "Intelligent Construction System"	1536
Shota Chikushi, Jun Younes Louhi Kasahara, Hiromitsu Fujii, Yusuke Tamura, Angela Faragasso, Hiroshi Yamakawa, Keiji Nagatani, Yonghoon Ji, Shinya Aoki, Takumi Chiba, Shingo Yamamoto, Kazuhiro Chayama, Atsushi Yamashita and Hajime Asama	

Automated Framework for the Optimisation of Spatial Layouts for Concrete Structures Reinforced with Robotic Filament Winding	1541
Robin Oval, Eduardo Costa, Diana Thomas-Mcewen, Saverio Spadea, John Orr and Paul Shepherd	
Adopting Off-site Manufacturing, and Automation and Robotics Technologies in Energy-efficient Building	1549
Wen Pan, Kepa Iturralde Lerchundi, Rongbo Hu, Thomas Linner and Thomas Bock	
Analysis on the Implementation Mechanism of an Inspection Robot for Glass Curtain Walls in High-rise Buildings	1556
Shiyao Cai, Zhiliang Ma and Jianfeng Guo	
Application of Robots to the Construction of Complex Structures using Standardized Timbers	1562
Yi Leng , Xingyu Shi and Fukuda Hiroatsu	
A Preliminary Comparison Between Manual and Robotic Construction of Wooden Structure Architecture	1568
Lu Wang, Hiroatsu Fukuda and Xinyu Shi	
Towards 3D Perception and Closed-Loop Control for 3D Construction Printing	1576
Xuchu Xu, Ruoyu Wang, Qiming Cao and Chen Feng	
Robotics Autonomous Surveillance Algorithms for Assessing Construction Automation and Completion Progress	1584
Firas Habbal, Abdulla AlNuaimi, Dhoha Alhmoudi, Mariam Alrayssi and Ahmed Alali	
Oscillation Reduction for Knuckle Cranes	1590
Michele Ambrosino, Arnaud Dawans, Brent Thierens and Emanuele Garone	
Bridge Inspection with Aerial Robots and Computer Vision: A Japanese National Initiative	1598
Jacob J. Lin, Amir Ibrahim, Shubham Sarwade, Mani Golparvar-Fard, Yasushi Nitta, Hirokuni Moirkawa and Yoshihiko Fukuchi	