ISARC 2020 Online

This is the final schedule of the program as of October 23, 2020. All times are in Japanese Standard Time (JST). Personalized ZOOM access links have been sent to all registered participants on October 23, 2020. Please check you spam folder, if needed. Those still registering on or after October 23, 2020 will receive their access links by the end of October 26, 2020 (JST).

Please note, some countries observe a time change the weekend before the ISARC 2020 Online will take place. To figure out your presentation time, add to the hours given in the schedule or use the link for your city.

+2 hours Sydney Tokyo 0 hours Beijing -1 hours New Delhi -3 hours 30 minutes Berlin -8 hours -9 hours London NYC -13 hours Los Angeles -16 hours Your city

Tuesday, October 27, 2020

08:00

ISARC Opening Ceremony

Tucker-Hasegawa 2020 Keynote - Smart Safety Assurance for Temporary Structures

Prof. Hyoungkwan Kim

		Track 1			Track 2			Track 3
Session		Automation and robotics	Session		Mixed themes	Session		Mixed themes
01	Paper ID	Session Chair: Genya Ishigami	02	Paper ID	Session Chair: Hiroshi Furuya	03	Paper ID	Session Chair: Anoop Sattineni
09:00	<u>78</u>	Application of robots to the construction of complex structures using standardized timbers Leng Yi, Shi Xinyu and Fukuda Hiroatsu	09:00	<u>79</u>	Rationalization of free-form surface construction method using wooden formwork Sei Hayashi and Tomoyuki Gondo	09:00	<u>379</u>	Scenario Based Construction Safety Training Platform Using Virtual Reality Ankit Gupta and Koshy Varghese
	<u>97</u>	An assistive interface of a teleoperation system of an excavator by overlapping the predicted position of the arm Yuzuki Okawa, Masaru Ito, Ryota Sekizuka, Seiji Saiki, Yoichiro Yamazaki and Yuichi Kurita		<u>156</u>	A systematic review of technical specification of 3D concrete printer Jihoon Chung, Ghang Lee and Jung-Hoon Kim		38	Field application of Tunnel Half Section Inspection System Nobukazu Kamimura, Satoru Nakamura, Daisuke Inoue and Takao Ueno
	111	Design and Construction of Shell-shaped Bench using a 3D Printer for Construction Hajime Sakagami, Haruna Okawa, Masaya Nakamura, Takuya Anabuki, Yoshikazu Ishizeki and Tomoya Kaneko		<u>120</u>	Visualization of the progress management of earthwork volume at construction jobsite Hajime Honda, Akifumi Minami, Yoshihiko Takahashi, Seishi Tajima, Takashi Ohtsuki and Yushi Shiiba		<u>175</u>	Report on the Measurement of the Form of SHOTCRETE GRID BEAM-FREE FRAME Using Point Cloud Data Kojima Takayuki and Yori Nomoto
	<u>95</u>	Proposal for automation system diagram and automation levels for earthmoving machine Takeshi Hashimoto, Mitsuru Yamada, Genki Yamauchi, Yasushi Nitta and Shinichi Yuta					223	Block Chain based Remicon Quality Managementr Seungwon Cho, Doyeop Lee and Chansik Park
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1			Track 2	Track 3			
Session 04	Paper ID	Mixed themes Session Chair: Xuesong Shen	Session 05	Paper ID	Building information modeling (BIM) Session Chair: Hung-Ming Chen	Session 06	Paper ID	Inspection and monitoring Session Chair: Mitsuhiro Kamezaki	
10:00	<u>127</u>	Constructible Design for Off-site Prefabricated Structures in Brownfield Environments: Review of Mixed Reality Applications Ankit Shringi, Mehrdad Arashpour and Arnaud Prouzeau	10:00	<u>14</u>	Five-dimensional Simulation of Bridge Engineering Based on BIM and VR Kun-Chi Wang, Sheng-Han Tung, Wei-Chih Chen and Zi-Chi Zhao	10:00	<u>80</u>	Challenges in working with the UAV image data of the construction sites Saurabh Gupta and Syam Nair	
	<u>5</u>	Real-time early warning of clogging risk in slurry shield tunneling: a self-updating machine learning approach Qiang Wang, Xiongyao Xie and Yu Huang		41	A Construction Progress On-site Monitoring and Presentation System Based on The Integration of Augmented Reality and BIM Sheng-Kai Wang and Hung-Ming Chen		<u>103</u>	Research and development on inspection technologz for afetz verification of small scale bridges using 3D model Kazuhiko Seki, Koichi lwasa, Satoshi Kubota, Yoshiniri Yasumuro and Ryuichi Imai	
	<u>17</u>	A Predictive Model for Scaffolding Man-hours Estimation in Heavy Industrial Construction Projects Wenjing Chu, Zhen Lei, Sanghyeok Han, Ulrich Hermann and Di Hu		<u>65</u>	System Development of an Augmented Reality Onsite BIM Viewer Based on the Integration of SLAM and BLE Indoor Positioning Yu-Cheng Liu, Jhih-Rong Chen and Hung-Ming Chen		114	Weakly Supervised Defect Detection using Acoustic Data based on Positive and Negative Constraints Jun Younes Louhi Kasahara, Atsushi Yamashita and Hajime Asama	
	118	Development of Cloud Computing System for Concrete Structure Inspection by Deep Learning Based Infrared Thermography Method Shogo Hayashi, Koichi Kawanishi, Isao Ujike and Pang-Jo Chun		<u>66</u>	An Information Quality Assessment Framework for Developing Building Information Models Liji Chen and K.W. Yeoh		113	Virtual Prototyping Based Path Planning of Unmanned Aerial Systems for Building Exterior Inspection Zhenjie Zheng, Mi Pan and Wei Pan	
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session	

Session 07	Al Paper ID	rtificial intelligence and machine learning Session Chair: Xuesong Shen	Session 08	Paper ID	Building information modeling (BIM) Session Chair: Furnihiro Inoue	Session 09	Paper ID	Inspection and monitoring Session Chair: Hiroshi Furuya
11:00	<u>132</u>	Optimal Travel Routes of On-road Vehicles Considering Sustainability	11:00	229	A framework for camera planning in construction site using 4D BIM and VPL	11:00	<u>115</u>	Road Maintenance Management System Using 3D Data by Terrestrial Laser Scanner and UAV
		Nassim Mehrvarz, Zhilin Ye, Khalegh Barati and Xuesong Shen MLIT's initiatives for promotion the efficient			Si Tran, Numan Khan, Doyeop Lee, Chansik Park and Ahmed Khairadeen Ali Automating crane lift path through integration of			Satoshi Kubota, Kotaro Nishi, Ryosuke Hata, Chiyuan Ho and Yoshihiro Yasumuro Development and verification of inspection method
	<u>195</u>	construction and inspection by using new technologies such as Al and robots in Japan. Kenichi Watanabe		<u>154</u>	BIM and path finding algorithm Songbo Hu and Yihai Fang		<u>178</u>	for concrete surface utilizing digital camera Shungo Matsui, Yoshimasa Nakata, Hidenori Shitashimizu, Ryota Nakatsuji, Takeshi Ueda and Naoki Maehara
	228	Accuracy and Generality of Trained Models for Lift Planning Using Deep Reinforcement Learning- Optimization of the Crane Hook Movement Between Aoi Tarutani and Kosei Ishida		<u>181</u>	A Web-Based Approach to Dynamically Assessing Space Conflicts by Integrating BIM and Graph Database Wei-Ting Chien and Shang-Hsien Hsieh		<u>187</u>	Automated On-Site Quality Inspection and Reporting Technology for Off-Site Construction(OSC)-based Precast Concrete Seojoon Lee, Soonwook Kwon, Minkyeong Jeong, Syedmobeen Hasan and Alexander Kim
	190	A study on an autonomous crawler carrier system with Al based transportation control Hironobu Hatamoto, Kazuya Fujimoto, Tsubasa Asuma, Yoshito Takeshita, Tetsuo Amagai, Atsushi Furukawa and Shigeo Kitahara					200	Research on a method to consider inspection and processing for atypical wood members using 3D laser scanning Shunsuke Someya, Yasushi Ikeda, Kensuke Hotta, Seigo Tanaka, Mizuki Hayashi, Mitsuhiro Jokaku and Taito Takahashi
1		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

Track 1					Track 2	Track 3		
Session 10	Aı Paper ID	tificial intelligence and machine learning Session Chair: Yasutoshi Nomura	Session 11	Paper ID	Building information modeling (BIM) Session Chair: Hyoungkwan Kim	Session 12	Paper ID	Inspection and monitoring Session Chair: Soungho Chae
12:00	343	Robotics autonomous surveillance algorithms for assessing construction automation and completion progress Firas Habbal, Ahmed Alali, Mariam Alrayssi, Abdualla Alnuaimi, Dhoha Alhmoudi and Dr. Fawaz Habbal	12:00	375	Status of 4D BIM Implementation in Indian Construction V. Paul C. Charlesraj and T. Dinesh	12:00	342	Cracks detection using artificial intelligence with deep learning to enhance inspection efficiency and analyze the critical defects Firas Habbal, Fawaz Habbal, Mohammed Al Shamsi, Thuraya Aldarmaki, Saleh Alshaibah and Abdualla Alnuaimi
	<u>374</u>	Action Recognition of Excavator using Simulated Training Data in Excavator Loading Trucks Jinhyeok Sim, Jun Younes Louhi Kasahara, Shota Chikushi, Hiroshi Yamakawa, Yusuke Tamura, Kejii Nagatani, Takumi Chiba, Shingo		401	Optimization of a Sustainable HVAC System Design Layout in BIM Environment Pouya Baradaran-Noveiri, Sang Hyeok Han and Mohammed Zaheeruddin		<u>226</u>	Stereo Vision based hazardous area detection for construction worker's safety Doyeop Lee, Numan Khan and Chansik Park
	300	Automatic Detection of Air Bubbles with Deep Learning Takuma Nakabayashi, Koji Wada and Yoshikazu Utsumi		<u>406</u>	Synthetic Data Generation for Indoor Scene Understanding Using BIM Yeji Hong, Somin Park and Hyoungkwan Kim		<u>231</u>	Optical Character Recognition and Blockchain- based inspection data recording system for portable firefighting equipment Numan Khan, Doyeop Lee, Ahmed Khairadeen Ali and Chansik Parl
	339	Digital Twin Technology Utilizing Robots and Deep Learning Fuminori Yamasaki					<u>319</u>	Generative Damage Learning for Concrete Aging Detection using Auto-flight Images Takato Yasuno, Akira Ishii, Junichiro Fujii, Masazumi Amakata and Yuta Takahashi
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

13:00	Break
14:00	Keynote 2 - International Space Exploration and Japanese Lunar Activities Naoki Sato 2021 ISARC Announcement

		Track 1			Track 2		Track 3		
Session	Ar	tificial intelligence and machine learning	Session		Construction management	Session		Inspection and monitoring	
13	Paper ID	Session Chair: Benny Raphael	14	Paper ID	Session Chair: Miho Makatayama	15	Paper ID	Session Chair: Bharadwaj Mantha	
15:00	<u>408</u>	Utilizing Al and machine learning for forecasting planning risks in construction Fawaz Habbal, Firas Habbal, Abdualla Alnuaimi, Anwar Alshimmari, Nawal Alhanaee and Ammar Safi	15:00	<u>240</u>	Decision Support System for Site Layout Planning Abhishek Raj Singh, Ankan Karmakar and Venkata Santosh Kumar Delhi	15:00	<u>348</u>	Development of Field View Monitor 2 -An assisting function for safety check around a hydraulic excavator using real-time image recognition with Susumu Aizawa, Yoshihisa Kiyota and Shunsuke Otsuki	
	<u>409</u>	Automated detection for road marking quality, using visual based machine learning Firas Habbal, Fawaz Habbal, Abdualla Alnuaimi, Shafia Alkheyaili and Ammar Safi		<u>367</u>	Overall utilization of Information and Communication Technologies in excavation work and management at Yoneshiro-gawa River, a first-class river Tatsuro Masu, Akihiro Ishii, Fumihiro Tamori, Hanako Hatakeyama, Yutaka Suzuki, Satoshi Shirato and Yurie Abe		<u>366</u>	Smart Tunnel Inspection and Assessment using Mobile Inspection Vehicle, Non-Contact Radar and Al Toru Yasuda, Hideki Yamamoto, Mami Enomoto and Yasushi Nitta	
	148	Improving Construction Project Schedule before Execution with Machine Learning Methods John Fitzsimmons, Ying Hong and Ioannis Brilakis		<u>369</u>	Stakeholder Perspectives on the Adoption of Drones in Construction Projects V. Paul C. Charlesraj and N. Rakshith		<u>368</u>	Development of ROV for visual inspection of concrete pier superstructure Toshinari Tanaka, Shuji Nogami, Ema Kato and Tsukasa Kita	
	377	Improvement of 3D modeling efficiency and accuracy of earthwork site by noise processing using deep learning and structure from motion Nobuyoshi Yabuki, Yukako Sakamoto and Tomohiro Fukuda		180	Constructability: The Prime Target in Value Engineering for Design Optimization Arun Sekhar and Uma Maheswari		<u>378</u>	Examination of efficiency of bridge periodic inspection using 3D data (point cloud data and images) Tatsuru Ninomiya, Mitsuharu Shimokawa, Tatsuya Hattori, Yasushi Nitta and Mami Enomoto	
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session	

Session		Mixed themes	Session		Mixed themes	Session		Construction management
16	Paper ID	Session Chair: Benny Raphael	17	Paper ID	Session Chair: Ammar Safi	18	Paper ID	Session Chair: Bharadwaj Mantha
16:00	<u>179</u>	An integrated sensor network method for safety management of construction workers	16:00	224	Blockchain based framework for verifying the adequacy of scaffolding installation	16:00	381	Scheduling Simulator by Ensemble Forecasting for Construction Duration
		Tingsong Chen, Nobuyoshi Yabuki and Tomohiro Fukuda			Chanwoo Baek, Doyeop Lee and Chansik Park			Shigeomi Nishigaki, Katsutoshi Saibara, Takashi Ootsuki and Hirokuni Morikawa
	<u>19</u>	Simulation-based Reinforcement Learning Approach towards Construction Machine Automation.		<u>263</u>	Multiple Tower Crane Selection methodology utilizing Genetic Algorithm		<u>98</u>	Review of Construction Work-Space Definition and Case Studies
		Keita Matsumoto, Atsushi Yamaguchi, Takahiro Oka, Masahiro Yasumoto, Satoru Hara, Michitaka lida and Marek Teichmann			Preet Lodaya, Abhishek Raj Singh and Venkata Santosh Kumar Delhi			Kuan-Fan Lai and Ying-Chieh Chan
		A Robust Framework for Identifying Automated			Current status of unmanned construction			Study on the level concept of autonomous
		Construction Operations			technology			construction in mechanized construction
	42	Aparna Harichandran, Benny Raphael and Abhijit Mukherjee		<u>305</u>	developed using a test field system Koji Ihara and Takeshi Tamura		<u>396</u>	Hirokuni Morikawa and Takashi Otsuki
		Development of A Mobile Robot pulling an Omni-			An analysis of 4D-BIM Construction Planning:			Research on standardization of construction site
		directional Cart for a Construction Site			Advantages, Risks and Challenges			time-series change information as learning data for
	<u>29</u>	Yusuke Takahashi, Yoshiro Hada and Satoru Nakamura		<u>87</u>	Pedram Farnood Ahmadi and Mehrdad Arashpour		397	automatic generation of work plan of construction Takashi Otsuki, Hirokuni Morikawa, Yushi Shiiba, Seigo Ogata and Masaharu Moteki
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1	Track 2				Track 3
Session 19		Mixed themes	Session 20		Mixed themes	Session 21	Mixed themes
	Paper ID	•		Paper ID	,		Paper ID
17:00		Real-time judgment of workload using heart rate	17:00		Generation of orthomosaic model for construction	17:00	
	<u>45</u>	and physical activity Nobuki Hashiguchi, Lim Yeongjoo, Cyo Sya, Kuroishi Shinichi, Yasuhiro Miyazaki, Shigeo Kitahara, Taizo Kobayashi, Kazuyoshi		<u>25</u>	site using unmanned aerial vehicile Alexey Bulgakov, Daher Sayfeddine, Thomas Bock and Awny Fares		
		A View of Construction Science and Robot			Ontological base for concrete bridge rehabilitation		
		technology implementation			projects		
	<u>121</u>			<u>20</u>			
		Hiroshi Yamamoto			Chengke Wu, Rui Jiang, Jun Wang, Jizhuo Huang and Xiangyu Wang		
		Traffic Regulation Technology by Movable Barriers			Training of Yolo neural network for the detection of		
	119			294	fire emergency asset		
		Toshiharu Tanikawa and Tohya Okishio			Alessandra Corneli, Berardo Naticchia, Frederic Bosché, Massimo Vaccarini and Alessandro Carbonari		
		Web-Based Communication Platform for Decision			BuiltView: Integrating LiDAR and BIM for Real-Time		
	139	Making in Early Design Phases		162	Quality Control of Construction Projects		
	133	Zhiwei Meng, Ata Zahedi and Frank Petzold		102	Rana Abbas, Christian Skinner, Monica Hanus-Smith, Andrew Harris and Nathan Kirchner		
		Q&A for all papers in this session			Q&A for all papers in this session		Q&A for all papers in this session

Session		Automation and robotics	Session		Building information modeling (BIM)	Session		Mixed themes
22	Paper ID	Session Chair: Wen Pan	23	Paper ID	Session Chair: Daniel Hall	24	Paper ID	Session Chair: Markus König
18:00	<u>43</u>	Design and Synthesis of the Localization System for the On-site Construction Robot: a case in Hong Kong Wen Pan, Rui Li and Thomas Bock	18:00	<u>140</u>	Ontology-based Product Configuration for Modular Buildings Jianpeng Cao and Daniel Hall	18:00	217	Deployment Of A Standardized BIM Modeling Guideline For The Planning And Construction Industry Manfred Helmus, Anica Meins-Becker, Gamze Hort and Daiki John Feller
	<u>69</u>	Analysis of Excavation Methods and Concept for a small-scale Mining Robot Michael Berner and Nikolaus August Sifferlinger		<u>141</u>	On Construction-Specific Product Structure Design and Development: The BIM Enhancement Approach Solmaz Mansoori, Harri Haapasalo and Janne Härkönen		100	Brian Klusmann, Zhiwei Meng, Anica Meins-Becker, Noemi Kremer and Manfred Helmus
	<u>124</u>	Robotic insertion of timber joints using visual detection of fiducial markers Nicolas Rogeau, Victor Tiberghien, Pierre Latteur and Yves Weinand		144	Parametric Structural Design for automated Multi- Objective Optimization of Flexible Industrial Buildings Julia Reisinger, Iva Kovacic and Maximilian Knoll		<u>67</u>	Rule-Based Generation of Assembly Sequences for Simulation in Large-Scale Plant Construction Jan Weber, Jana Stolipin, Markus König, Sigrid Wenzel and Ulrich Jessen
	<u>55</u>	Laser Scanner Automation for an Industrial Robot Petras Vestartas and Yves Weinand		<u>149</u>	Development of an Open Source Scan&BIM Platform Enrique Valero, Dibya D. Mohanty and Frederic Bosche		<u>126</u>	Integrating BIM- and cost-included information container with Blockchain for construction automated payment using billing model and smart Xuling Ye, Katharina Sigalov and Markus König
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

	Track 1	Track 2	Track 3
19:00			
		Break	

Session		Mixed themes	Session		Construction management	Session		Safety and health
25	Paper ID	Session Chair: Jochen Teizer	26	Paper ID	Session Chair: Daniel Hall	27	Paper ID	Session Chair: Rongbo Hu
20:00		Automatized Parametric Modeling to Enhance a	20:00		Incentivizing High-Quality Data Sets in	20:00		Developing a Windshield Display for Mobile Cranes
	242	data-based Maintenance Process for Infrastructure		121	Construction Using Blockchain: A Feasibility Study		127	
	<u>212</u>	Buildings		<u>131</u>	in the Swiss Industry		<u>137</u>	
		Robert Hartung, Robin Schönbach, Dominic Liepe and Katharina Klemt-Albert			Jens J. Hunhevicz, Tobias Schraner and Daniel M. Hall			Taufik Akbar Sitompul, Simon Roysson and José Rosa
		An automated approach to digitize masonry			Design for digital fabrication: an industry needs			Exploring Gerontechnology for Aging-Related
		bridges			analysis of collaboration platforms and integrated			Diseases in Design Education: An Interdisciplinary
	<u>372</u>			<u>250</u>	management processes		<u>32</u>	Perspective
		Mustafa Al-Adhami, Sagal Rooble, Song Wu, Clara Osuna-Yevenes, Veronica Ruby-Lewis, Mark. Greatrix, Yreilyn Cartagena and Saeed			Ming Shan Ng, Marcella M. Bonanomi, Daniel M. Hall and Jürgen Hackl			Rongbo Hu, Thomas Linner, Marc Schmaitzl, Jörg Güttler, Yuan Lu and Thomas Bock
		Safe and Lean Location-based Construction			A Shared Ontology for Logistics Information			Development of a twin model for real-time detection
		Scheduling			Management in the Construction Industry			of fall hazards
	<u>235</u>			<u>68</u>			<u>201</u>	
		Beidi Li, Carl Schultz, Jürgen Melzner, Olga Golovina and Jochen Teizer			Yuan Zheng, Müge Tetik, Seppo Törmä, Antti Peltokorpi and Olli Seppänen			Leonardo Messi, Alessandra Corneli, Massimo Vaccarini and Alessandro Carbonari
		Cyber-physical system for diagnosing and			Single shared model approach for building			Data-Driven Worker Detection from Load-View
		predicting the technical condition of servo-drives		202	information modelling		206	Crane Camera
	44	of a mechatronic sliding complex during the Alexey Bulgakov, Thomas Bock and Tatiana Kruglova		392	Simo Ruokamo and Heikkilä Rauno		<u>206</u>	Tanittha Sutjaritvorakul, Axel Vierling and Karsten Berns
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1			Track 2	Track 3		
Session		Mixed themes	Session		Construction management	Session		Mixed themes
28	Paper ID	Session Chair: Frédéreic Bosché	29	Paper ID	Session Chair: Zhenhua Zhu	30	Paper ID	Session Chair: Vineet Kamat
21:00		A Holistic Framework for the Implementation of Big	21:00		A Vision for and Evaluations of Responsive	21:00		Factors affecting the implementation of Al-bsed
	150	Data throughout a Construction Project Lifecycle		0.4	Environments in Future Medical Facilities		244	hearing protection technology at construction
	<u>150</u>	Makram Bou Hatoum, Melanie Piskernik and Hala Nassereddine		94	Daniel Lu, Semiha Ergan, Devin Mann and Katharine Lawrence		244	workplace Yongcan Huang and Tuyen Le
		Towards a computational approach to quantify human experience in urban design: Data collection			Construction 4.0: A roadmap to shaping the future of Construction			A novel audio-based machine learning model for automated detection of collision hazards at
	<u>315</u>	phase Keundeok Park and Semiha Ergan		<u>292</u>	Mahmoud El Jazzar, Harald Urban, Christian Schranz and Hala Nassereddine		<u>271</u>	construction sites Khang Dang and Tuyen Le
	<u>60</u>	Efficient Numerical Methods for Accurate Modeling of Soil Cutting Operations		92	Energy Performance and LCA-driven Computational Design Methodology for Integrating Modular Construction in Adaptation of Concrete		<u>356</u>	Real-Time Process-Level Digital Twin for Collaborative Human-Robot Construction Work
		Amin Haeri, Dominique Tremblay, Krzysztof Skonieczny, Daniel Holz and Marek Teichmann			Sheida Shahi, Patryk Wozniczka, lan Trudeau, Tristan Truyens and Carl Haas			Xi Wang, Ci-Jyun Liang, Carol Menassa and Vineet Kamat
	<u>276</u>	Ontology-Based Decoding of Risks Encoded in the Prescriptive Requirements in Bridge Design Codes		280	Analyzing Idling Reasons Based on Excavator- truck Relationships in Earthwork Operations		412	Bridge Inspection with Aerial Robots and Computer Vision: A Japanese National Initiative
		Fahad Ul Hassan and Tuyen Le			Chen Chen, Zhenhua Zhu and Amin Hammad			Jacob J. Lin, Amir Ibrahim, Shubham Sarwade, Mani Golparvar-Fard, Yasushi Nitta, Hirokuni Moirkawa and Yoshihiko Fukuchi
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

Session 31		Mixed themes	Session 32		Data sensing and analysis	Session 33		Mixed Realities (AR/VR)
31	Paper ID	Session Chair: Burcu Akinci	32	Paper ID	Session Chair: Yong Cho	33	Paper ID	Session Chair: Alessandro Carbonari
22:00	<u>90</u>	Parametric or Non-Parametric? Understanding the Inherent Trade-offs between forms of Object Representation	22:00	<u>30</u>	Automated Data Acquisition for Indoor Localization and Tracking of Materials on Site	22:00	<u>273</u>	Development of an Augmented Reality Fitness Index for Contractors
		Christopher Rausch, Yinghui Zhao and Carl Haas			Hassan Bardareh and Osama Moselhi			Hala Nassereddine, Awad Hanna, Wafik Lotfallah and Dharmaraj Veeramani
		Integrating Industry 4.0 associated technologies			Workspace Modeling: Visualization and Pose			The Impact of Integrating Augmented Reality into
		into Automated and tradidional Construction			Estimation of Teleoperated Construction			the Production Strategy Process
	309			<u>57</u>	Equipment from Point Clouds		<u>275</u>	
		Fabiano Correa			Jing Dao Chen, Pileun Kim, Dong-lk Sun, Chang-Soo Han, Yong Han Ahn, Jun Ueda and Yong Cho			Hala Nassereddine, Dharmaraj Veeramani and Awad Hanna
		Maintenance of buildings: A closer look at façades			A Deep Learning-based Approach for Detecting			Using a Virtual Reality-based Experiment
		and façade inspection reports			Construction Machinery in Jobsites Using Mask R-			Environment to Examine Risk Habituation in
	<u>253</u>	Zhuoya Shi, Keundeok Park and Semiha Ergan	2	<u>72</u>	CNN Hamed Raoofi and Ali Motamedi		313	Construction Safety Namgyun Kim and Changbum Ryan Ahn
		Project work breakdown structure similarity			Evaluation of Spalling in Bridges Using Machine			A Framework for Augmented Reality Assisted
	247	estimation using semantic and structural similarity		116	Vision Method		400	Structural Embedment Inspection
	<u>247</u>	measures Navid Torkanfar and Ehsan Rezazadeh Azar		<u>116</u>	Eslam Mohammed Abdlekader, Osama Moselhi, Mohamed Marzouk and Tarek Zayed		400	Jeffrey Kim and Darren Olsen
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

	Track 1				Track 2	Track 3		
Session 34	Paper ID	Mixed themes Session Chair: Vineet Kamat	Session 35	Ar Paper ID	rtificial intelligence and machine learning Session Chair: Saiedeh Razavi	Session 36	Paper ID	Mixed themes Session Chair: Yelda Turkan
08:00	341	Bi-Directional Communication Bridge for State Synchronization between Digital Twin Simulations and Physical Construction Robots Ci-Jyun Liang, Wes Mcgee, Carol Menassa and Vineet Kamat	08:00	11	Automated Road Pavement Defects Detection and Classification Andrea Leal Ruiz and Hani Alzraiee	08:00	324	ABM and GIS for Wildfire Management Qi Sun and Yelda Turkan
	414	Quality Control for Concrete Steel Embed Plates using LiDAR and Point Cloud Mapping Hani Alzraiee, Robert Sprotte and Andrea Leal Ruiz		270	Fuzzy Controller Algorithm for Automated HVAC Control Myungjin Chae, Kyubyung Kang, Dan D. Koo, Sukjoon Oh and Jae Youl Chun		314	Augmented Reality Sandboxes for Civil and Construction Engineering Education Joseph Louis and Jennifer Lather
	<u>159</u>	Development of simple attachment for remote control (Doka Touch) Kazuki Sumi		<u>302</u>	Condition Prediction of Highway Assets Based on Spatial Proximity and Interrelations of Asset Classes: A Case Study Arash Karimzadeh, Sepehr Sabeti, Hamed Tabkhi and Omidreza Shoghli		<u>398</u>	A Technology Platform for a Successful Implementation of Integrated Project Delivery for Medium Size Projects Luke Posomas and Hani Alzraiee
	192	Towards 3D Perception and Closed-Loop Control for 3D Construction Printing Xuchu Xu, Ruoyu Wang, Qiming Cao and Chen Feng		310	Using Deep Learning for Assessment of Workers' Stress and Overload Sahel Eskandar and Saiedeh Razavi		<u>89</u>	Implementation of unsupervised learning methods in rule learning from construction schedules Boong Yeol Ryoo and Milad Ashtab
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

Session		Automation and robotics	Session		Mixed themes	Session		Mixed themes
37	Paper ID	Session Chair: Jack C. P. Cheng	38	Paper ID	Session Chair: Saiedeh Razavi	39	Paper ID	Session Chair: Yelda Turkan
09:00	<u>194</u>	BIM-Aided Scanning Path Planning for Autonomous Surveillance UAVs with LiDAR Changhao Song, Kai Wang and Jack C. P. Cheng	09:00	<u>152</u>	Comparison of Shortest Path Finding Algorithms for Power and Instrument Cables in Industrial Construction Projects Fatima Alsakka, Salam Khalife, Maram Nomir, Yasser Mohamed and Rick Hermann	09:00	<u>59</u>	A Critical Review of Machine Vision Applications in Construction Saeed Ansari Rad and Mehrdad Arashpour
	<u>196</u>	Preliminary Development of a Powerful and Backdrivable Robot Gripper Using Magnetorheological Fluids Sahil Shembekar, Mitsuhiro Kamezaki, Peizhi Zhang, Zhouyi He, Ryuichiro Tsunoda, Kenshiro Otsuki, Hiroyuki Sakamoto and Shigeki		<u>184</u>	Financial Modeling for Modular and Offsite Construction Tarek Salama, Gareth Figgess, Mohamed Elsharawy and Hossam Elsokkary		<u>18</u>	Applications of building information modeling (BIM) in disaster resilience: Present status and future trends Sadegh Khanmohammadi, Mehrdad Arashpour and Yu Bai
	233	Reaching difficulty model of swinging operations of a hydraulic excavator considering the first-order delay Kazuyuki Matsumura, Masaru Ito, Chiaki Raima, Seiji Saiki, Yoichiro Yamazaki and Yuichi Kurita		402	Introduction of the new safety concept "Safety2.0"to reduce the risk of machinery accidents Hidesato Kojima, Takaya Fujii, Yasushi Mihara and Hiroaki Ihara		<u>173</u>	An Agent-based Framework for Evaluating Location- based Risk in Indoor Emergency Evacuation Tianlun Cai, Jiamou Liu, Hong Zheng, Yupan Wang and Vicente Gonzalez
	204	Development of fireproof coating spraying robot and Application of building construction site Yuichi Ikeda, Hirofumi Segawa and Nobuyoshi Yabuki		<u>198</u>	A Novel Methodological Framework of Smart Project Delivery of Modular Integrated Construction Wei Pan, Mi Pan and Zhenjie Zheng		<u>259</u>	Track Similarity-based Typhoon Search Engine for Disaster Preparedness Chun-Mo Hsieh, Cheng-Yu Ho, Hung-Kai Kung, Hao-Yung Chan, Meng-Han Tsai and Yun-Cheng Tsai
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1			Track 2			Track 3
Session		Automation and robotics	Session		Data sensing and analysis	Session		Safety and health
40	Paper ID	Session Chair: Chen Feng	41	Paper ID	Session Chair: Koshy Varghese	42	Paper ID	Session Chair: Castro-Lacouture
10:00	<u>345</u>	Autonomous Excavation in Consideration of Soil Properties	10:00	<u>85</u>	loT-enabled dependable co-located low-cost sensing for construction site monitoring	10:00	199	Safety monitoring of construction equipment based on multi-sensor technology
		Shinya Katsuma, Ryosuke Yajima, Shunsuke Hamasaki, Pang-Jo Chun, Keiji Nagatani, Genki Yamauchi, Takeshi Hashimoto, Atsushi			Huynh A.D. Nguyen, Lanh V. Nguyen and Quang P. Ha			Ziqing Yang, Jian Yang and Enliu Yuan
	<u>349</u>	Development of an algorithm for crane sway suppression		<u>125</u>	IoT Enabled Framework for Real-time Management of Power-Tools at Construction Projects		<u>362</u>	Incident Detection at Construction Sites via Heart- Rate and EMG Signals of Facial Muscle
		Yasuhiro Yamamoto, Chunnan Wu, Hisashi Osumi, Masayuki Yano and Yusuke Hara			Ashish Kumar Saxena, Varun Kumar Reja and Koshy Varghese			Mizuki Sugimoto, Shunsuke Hamasaki, Ryosuke Yajima, Hiroshi Yamakawa, Kaoru Takakusaki, Keiji Nagatani, Atsushi Yamashita and
	<u>350</u>	Analysis of energy efficiency of a backhoe during digging operation Yusuke Sano, Chunnan Wu, Hisashi Osumi, Yuki Kawashima and		<u>128</u>	Measuring adhesion strength of the wall tile to concrete by Non-contact Inspection using Electromagnetic Waves		<u>399</u>	Development of an Automated Angle Control System to Improve Safety and Productivity
		Tomoaki Tsuda			Hussain Alsalem, Takayuki Tanaka, Takumi Honda, Satoru Doi and Shigeru Uchida			Tsuyoshi Fukuda, Takumi Arai, Kousuke Kakimi and Keishi Matsumoto
	<u>351</u>	Remote Control Demonstration of the Construction Machine using 5G Mobile Communication System at Tunnel Construction Site		<u>155</u>	Toolbox Spotter: A Computer Vision System for Real World Situational Awareness in Heavy Industries		<u>197</u>	Safety concept and architecture for autonomous haulage system in mining
		Ken Takai, Hiroaki Aoki, Yusuke Tajima and Michinobu Yoshida			Stuart Eiffert, Alex Wendel, Peter Colborne-Veel, Nicholas Leong, John Gardenier and Nathan Kirchner			Hidefumi Ishimoto and Tomoyuki Hamada
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

Session		Automation and robotics	Session		Data sensing and analysis	Session		Mixed Realities (AR/VR)
43	Paper ID	Session Chair: Yasushi Nitta	44	Paper ID	Session Chair: Soonwook Kwon	45	Paper ID	Session Chair: Tomohiro Umetani
11:00	<u>353</u>	Sea Experiment on Tele-operation System of Underwater Excavator Tsukasa Kita, Taketsugu Hirabayashi, Ueyama Atsushi, Hiroshi Kinjo, Naoki Oshiro and Nobuyuki Kinjo	11:00	<u>160</u>	Construction Method of Super Flat Concrete Slab using High Precision Height Measurement Yutaro Fukase, Ryosuke Saito, Yoshiaki Takemoto and Muramatsu Yoshiki	11:00	<u>143</u>	Near Real-Time Monitoring of Construction Progress: Integration of Extended Reality and Kinect V2 Ahmed Khairadeen Ali, One Jae Lee and Chansik Park
	123	Development of rotary snowplow driving support system using quasi-zenit satellite on expressway in Hokkaido Atsushi Ichikawa, Katsuyoshi Abe, Toshiaki Itou and Keigo Kurihara		<u>183</u>	Single Camera Worker Detection, Tracking and Action Recognition in Construction Site Hiroaki Ishioka, Xinshuo Weng, Yunze Man and Kris Kitani		<u>186</u>	VRGIare: A Virtual Reality Lighting Performance Simulator for real-time Three-Dimensional Glare Simulation and Analysis Kieran May, James Walsh, Ross Smith, Ning Gu and Bruce Thomas
	122	A Preliminary Comparison Between Manual and Robotic Construction of Wooden Structure Architecture Lu Wang, Hiroatsu Fukuda and Xinyu Shi		<u>185</u>	MR-based equipment remote control and 3D digital working guidance for field-oriented maintenance Jinwoo Song, Kyuhyup Lee, Minkyeong Jeong, Seojoon Lee and Soonwook Kwon		232	Inspection of discrepancies in Construction Temporary Safety Structures through Augmented Reality Hashim Raza Bokhari, Doyeop Lee, Numan Khan and Chansik Park
	<u>394</u>	Automation and operation record of large overhead crane for segment transportation Yasushi Nishizaki		<u>168</u>	Method for estimating subgrade reaction modulus by measuring wheel-terrain interactions Yasushi Wada and Taizo Kobayashi		<u>371</u>	Image analysis of eye movement in VR-video based experiments for detecting dengerous situations in construction site Shunsuke Hamasaki, Mizuki Sugimoto, Ryosuke Yajima, Atsushi Yamashita, Keiji Nagatani and Hajime Asama
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1			Track 2	Track 3		
Session 46	Paper ID	Automation and robotics Session Chair: Soungho Chae	Session 47	Paper ID	Data sensing and analysis Session Chair: Taizo Kobayashi	Session 48	Paper ID	Data sensing and analysis Session Chair: Hisashi Osumi
12:00	61	An agent-based approach for modeling human- robot collaboration in bricklaying	12:00	188	Use of laser scanning, remote sensors and traffic data collection, drones and mobile application. MoEl Federal Highways network case study.	12:00	361	Development of a Workers' Behavior Estimation System Using Sensing Data and Machine Learning
	<u>76</u>	Ming-Hui Wu and Jia-Rui Lin Analysis on the implementation mechanism of an inspection robot for glass curtain walls in high-rise buildings Shiyao Cai, Zhiliang Ma and Jianfeng Guo		225	Habiba Noor Aflatoon, Daniel Llort Mac Donald and Khamis Alsheyahri Autonomous UAV Flight using Total Station Navigation System in Non-GNSS Environments Akira Ishii, Takato Yasuno, Masazumi Amakata, Hiroaki Sugawara, Junichiro Fujii and Kohei Ozasa		380	Rikuto Tanaka, Nobuyoshi Yabuki and Tomohiro Fukuda Cyber Agent to Support Workers' Decision Making for Construction Shigeomi Nishigaki, Katsutoshi Saibara, Takashi Ootsuki and Hirokuni Morikawa
	<u>77</u>	Curtain Wall Installation for High-Rise Buildings: Critical Review of Current Automation Solutions and Opportunities Brandon Johns, Mehrdad Arashpour and Elahe Abdi		<u>245</u>	Evaluating slam 2D and 3D mapping of indoor structures Yoshihiro Nitta, Derbew Yenet Bogale, Yorimasa Kuba and Zhang Tian		<u>384</u>	Experimental result of third person's view generation from omni-directional camera Akira Sakata, Yasushi Hada, Rei Hojo, Masahiro Munemoto, Yoshito Takeshita, Tsubasa Asuma and Shigeo Kitahara
	<u>96</u>	Threat Modeling in Construction: An Example of a 3D Concrete Printing System Maahir Ur Rahman Mohamed Shibly and Borja Garcia de Soto		334	Streamlining Photogrammetry-based 3D Modeling of Construction Sites using a Smartphone, Cloud Service and Best-view Guidance Ryota Moritani, Satoshi Kanai, Kei Akutsu, Kiyotaka Suda, Abdalrahman Eishafey, Nao Urushidate and Mitsuru Nishikawa		<u>340</u>	Evaluation method for drainage gradient using 3D measurement data and a physics engine Kosei Ishida
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

13:00	Break
14:00	Keynote 3 - Initiatives for Robot Introduction in Japanese Public Works Dr. Yasushi Nitta 2021 ISARC Announcement

		Track 1			Track 2	Track 3		
Session 49		Automation and robotics	Session 50		Automation and robotics	Session 51		Education
	Paper ID	·		Paper ID	•		Paper ID	., ., .,
15:00	<u>147</u>	Modeling and control of a 5-Dof boom crane	15:00	6	Design-to-Robotic-Production and -Assembly for Architectural Hybrid Structures	15:00	<u>138</u>	Changing Paradigm: a Pedagogical Method of Robotic Tectonics into Architectural Curriculum
		Michele Ambrosino, Emanuele Garone, Marc Berneman, Gianluca Carbone, Rémi Crépin and Arnaud Dawans		_	Henriette Bier, Arwin Hidding and Marco Galli			Xinyu Shi, Xue Fang, Zhoufan Chen, Tyson Keen Phillips and Hiroatsu Fukuda
	<u>193</u>	Requirements for safe operation and facility maintenance of the construction robots Alexey Bulgakov, Thomas Bock, Jens Otto and Natalia Buzalo		<u>8</u>	Towards Circular Economy in Architecture by Means of Data-driven Design-to- Robotic- Production Ginevra Nazzarri and Henriette Bier		<u>382</u>	Research and Development of Construction Technology in Social Cooperation Program "Intelligent Construction System" Shota Chikushi, Jun Younes Louhi Kasahara, Hiromitsu Fujii, Yusuke Tamura, Angela Faragasso, Hiroshi Yamakawa, Keiji Nagatani,
	213	Online Synchronization of Building Model for On- Site Mobile Robotic Construction Selen Ercan Jenny, Hermann Blum, Abel Gawel, Roland Siegwart, Fabio Gramazio and Matthias Kohler		21	Optimization of Trajectories for Cable Robots on Automated Construction Sites Roland Boumann, Tobias Bruckmann, Patrik Lemmen and Robin Heidel		248	Gamification and BIM - Teaching the BIM method through a gamified, collaborative approach Carla Pütz, Christian Heins, Manfred Helmus and Anica Meins-Becker
	218	A Methodology to Monitor Construction Progress Using Autonomous Robots Samuel A. Prieto, Borja Garcia de Soto and Antonio Adan		<u>40</u>	Adopting off-site manufacturing, and automation and robotics technologies in energy-efficient building Wen Pan, Kepa Iturralde Lerchundi, Marcel Schlandt, Rongbo Hu, Thomas Linner and Thomas Bock		390	Education of Open Infra BIM based Automation and Robotics Heikkilä Rauno and Kolli Tanja
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

Session		Automation and robotics	Session		Data sensing and analysis	Session		Mixed themes
52	Paper ID	Session Chair: Borja Garcia de Soto	53	Paper ID	Session Chair: Thomas Linner	54	Paper ID	Session Chair: Hyoungkwan Kim
16:00	234	Towards High-Quality Road Construction: Using Autonomous Tandem Rollers for Asphalt Compaction Optimization Patrick Wolf, Jörg Husemann, Axel Vierling, Karsten Berns and Peter Decker	16:00	403	A Simulation Approach to Optimize Concrete Delivery using UAV Photogrammetry and Traffic Data Robert Sprotte and Hani Alzraiee	16:00	<u>15</u>	Improving Construction Demonstrations by Integrating BIM, UAV, and VR Kun-Chi Wang, Ren-Jie Gao, Sheng-Han Tung and Yuan-Hsiu Chou
	237	Mechatronic control system for leveling of bulldozer blade Alexey Bulgakov, Thomas Bock and Georgii Tokmakov		411	Mirror-aided approach for surface flatness inspection using laser scanning Fangxin Li and Min-Koo Kim		<u>251</u>	Opportunities and Challenges of Digital Twin Applications in Modular Integrated Construction Mingcheng Xie and Wei Pan
	<u>252</u>	A Cable Driven Parallel Robot with a Modular End Effector for the Installation of Curtain Wall Modules Kepa Iturralde, Malte Feucht, Rongbo Hu, Wen Pan, Marcel Schlandt, Thomas Linner, Thomas Bock, Jean-Bapliste Izard, Ibon Eskudero,		<u>108</u>	Applications of LiDAR for productivity improvement on construction projects: case studies from active sites Fredrik Westling, Rana Abbas, Christian Skinner, Monica Hanus-Smith, Andrew Harris and Nathan Kirchner		<u>363</u>	Deep Learning-based Question Answering System for Proactive Disaster Management Yohan Kim, Jiu Sohn, Seongdeok Bang and Hyoungkwan Kim
	<u>257</u>	On-site Autonomous Construction Robots: A review of research areas, technologies, and suggestions for advancement Xinghui Xu and Borja Garcia de Soto		130	Constraint Control for a Underactuated Boom Crane System Michele Ambrosino, Emanuele Garone and Arnaud Dawans		<u>26</u>	Using Virtual Reality and Augmented Reality for Presale House Customer Change Ben Amed Ouedraogo, Li-Chuan Lien, Unurjargal Dolgorsuren and Yan Ni Liu
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

		Track 1			Track 2	Track 3		
Session		Automation and robotics	Session		Data sensing and analysis	Session		Mixed themes
55	Paper ID	Session Chair: Kazuo Ishii	56	Paper ID	Session Chair: Thomas Linner	57	Paper ID	Session Chair: Ronie Navon
17:00	<u>279</u>	A probabilistic motion control approach for teleoperated construction machinery	17:00	<u>265</u>	Depth-Camera-Based In-line Evaluation of Surface Geometry and Material Classification For Robotic Spraying	17:00	<u>246</u>	Don't risk your real estate - Actions to realize efficient project risk management using the BIM method
	386	Hyung Joo Lee and Sigrid Brell-Cokcan Oscillation reduction for knuckle cranes Michele Ambrosino, Emanuele Garone, Brent Thierens and Arnaud		<u>267</u>	Valens Frangez, David Salido-Monzú and Andreas Wieser Automatic Geometric Digital Twin Generation of Railway Overhead Line Equipment from Airborne LiDAR Data MR Mahendrini Fernando Ariyachandra and Ioannis Brilakis		<u>272</u>	Maike Eilers, Carla Pütz, Manfred Helmus and Anica Meins-Becker A conceptual model for transformation of bill of materials from offsite manufacturing to onsite construction in industrialized house-building Raafat Hussamadin, Mikael Tallgren and Gustav Jansson
	387	Dawans Automated framework for the optimisation of spatial layouts for concrete structures reinforced with robotic filament winding Robin Oval, Eduardo Costa, Diana Thomas-Mcewen, Saverio Spadea, John Orr and Paul Shepherd		405	Construction operation assessment and correction using laser scanning and projection feedback Alexei Pevzner, Saed Hasan, Rafael Sacks and Amir Degani		<u>274</u>	Combining Reality Capture and Augmented Reality to visualise subsurface utilities in the field Lasse Hedegaard Hansen, Simon Swanström Wyke and Erik Kjems
	410	Parallel kinematic construction robot for AEC industry Maike Klöckner, Mathias Haage, Klas Nilsson, Anders Robertsson and Ronny Andersson		<u>10</u>	OpenBridgeGraph: Integrating Open Government Data for Bridge Management Jia-Rui Lin		<u>277</u>	A method to produce & visualize interactive work instructions for modular products within onsite construction Raafat Hussamadin, Jani Mukkavaara and Gustav Jansson
		Q&A for all papers in this session			Q&A for all papers in this session			Q&A for all papers in this session

18:00	
	Awards and Closing Ceremony